

Motion SPM[®] 45 Series

FNA41560T2

General Description

FNA41560T2 is a Motion SPM 45 module providing a fully-featured, high-performance inverter output stage for AC Induction, BLDC, and PMSM motors. These modules integrate optimized gate drive of the built-in IGBTs to minimize EMI and losses, while also providing multiple on-module protection features including under-voltage lockouts, over-current shutdown, thermal monitoring of drive IC, and fault reporting. The built-in, high-speed HVIC requires only a single supply voltage and translates the incoming logic-level gate inputs to the high-voltage, high-current drive signals required to properly drive the module's internal IGBTs. Separate negative IGBT terminals are available for each phase to support the widest variety of control algorithms.

Features

- UL Certified No. E209204 (UL1557)
- 600 V – 15 A 3-Phase IGBT Inverter with Integral Gate Drives and Protection
- Low Thermal Resistance Using Ceramic Substrate
- Low-Loss, Short-Circuit-Rated IGBTs
- Built-In Bootstrap Diodes and Dedicated Vs Pins Simplify PCB Layout
- Built-In NTC Thermistor for Temperature Monitoring
- Separate Open-Emitter Pins from Low-Side IGBTs for Three-Phase Current Sensing
- Single-Grounded Power Supply
- Isolation Rating of 2000 Vrms / 1 min.
- This is a Pb-Free and Halogen Free/BFR Free Device

Applications

- Motion Control – Home Appliance / Industrial Motor

Related Resources

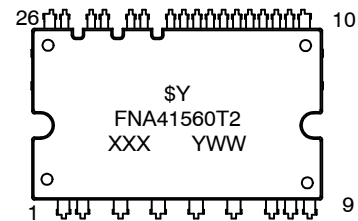
- [AN-9084 – Smart Power Module, Motion SPM[®] 45 H V3 Series User's Guide](#)
- [AN-9072 – Smart Power Module Motion SPM[®] in SPM45H Thermal Performance Information](#)
- [AN-9071 – Smart Power Module Motion SPM[®] in SPM45H Mounting Guidance](#)
- [AN-9760 – PCB Design Guidance for SPM[®]](#)



3D Package Drawing (Click to Activate 3D Content)

**SPMAA-C26 / 26LD, PDD STD CERAMIC TYPE,
LONG LEAD DUAL FORM TYPE
CASE MODFC**

MARKING DIAGRAM



\$Y = onsemi Logo
FNA41560T2 = Specific Device Code
XXX = Trace Code
Y = Year
WW = Work Week

ORDERING INFORMATION

See detailed ordering and shipping information on page 14 of this data sheet.

Integrated Power Functions

- 600 V – 15 A IGBT inverter for three-phase DC / AC power conversion (refer to Figure 2)

Integrated Drive, Protection, and System Control Functions

- For inverter high-side IGBTs:
gate-drive circuit, high-voltage isolated high-speed level-shifting control circuit,
Under-Voltage Lock-Out Protection (UVLO)

NOTE: Available bootstrap circuit example is given in Figures 14

- For inverter low-side IGBTs:
gate-drive circuit, Short-Circuit Protection (SCP)
control supply circuit,
Under-Voltage Lock-Out Protection (UVLO)

- Fault signaling:
corresponding to UVLO (low-side supply) and SC faults
- Input interface:
active-HIGH interface, works with 3.3 / 5 V logic, Schmitt-trigger input

Pin Configuration

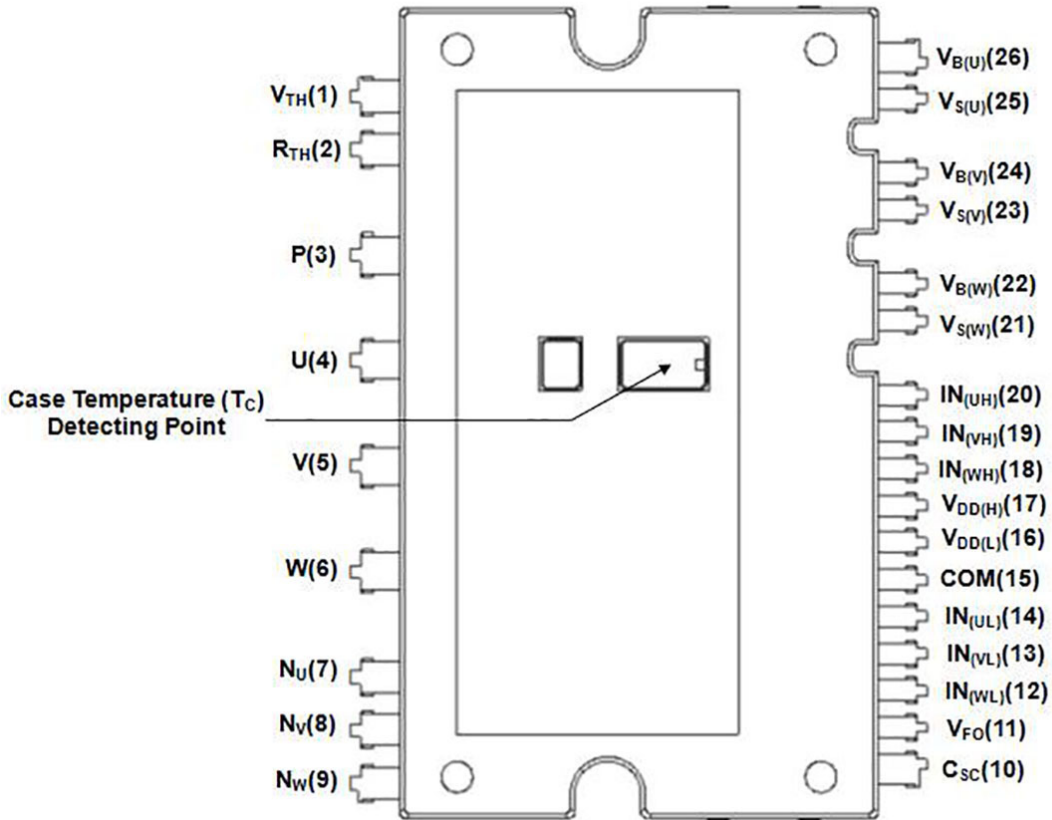


Figure 1. Top View

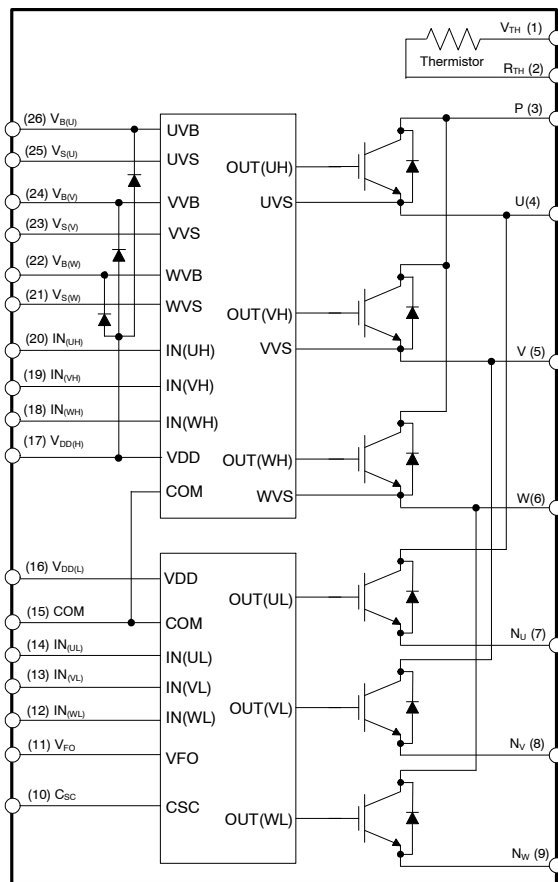
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PIN DESCRIPTIONS

Pin No.	Pin Name	Pin Description
1	V_{TH}	Thermistor Bias Voltage
2	R_{TH}	Series Resistor for the Use of Thermistor (Temperature Detection)
3	P	Positive DC-Link Input
4	U	Output for U-Phase
5	V	Output for V-Phase
6	W	Output for W-Phase
7	N_U	Negative DC-Link Input for U-Phase
8	N_V	Negative DC-Link Input for V-Phase
9	N_W	Negative DC-Link Input for W-Phase
10	C_{SC}	Shut Down Input for Short-circuit Current Detection Input
11	V_{FO}	Fault Output
12	$IN_{(WL)}$	Signal Input for Low-Side W-Phase
13	$IN_{(VL)}$	Signal Input for Low-Side V-Phase
14	$IN_{(UL)}$	Signal Input for Low-Side U-Phase
15	COM	Common Supply Ground
16	$V_{DD(L)}$	Low-Side Common Bias Voltage for IC and IGBTs Driving
17	$V_{DD(H)}$	High-Side Common Bias Voltage for IC and IGBTs Driving
18	$IN_{(WH)}$	Signal Input for High-Side W-Phase
19	$IN_{(VH)}$	Signal Input for High-Side V-Phase
20	$IN_{(UH)}$	Signal Input for High-Side U-Phase
21	$VS_{(W)}$	High-Side Bias Voltage Ground for W-Phase IGBT Driving
22	$VB_{(W)}$	High-Side Bias Voltage for W-Phase IGBT Driving
23	$VS_{(V)}$	High-Side Bias Voltage Ground for V-Phase IGBT Driving
24	$VB_{(V)}$	High-Side Bias Voltage for V-Phase IGBT Driving
25	$VS_{(U)}$	High-Side Bias Voltage Ground for U-Phase IGBT Driving
26	$VB_{(U)}$	High-Side Bias Voltage for U-Phase IGBT Driving

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Internal Equivalent Circuit and Input/Output Pins



NOTES:

1. Inverter high-side is composed of three normal-IGBTs, freewheeling diodes, and one control IC for each IGBT.
2. Inverter low-side is composed of three sense-IGBTs, freewheeling diodes, and one control IC for each IGBT. It has gate drive and protection functions.
3. Inverter power side is composed of four inverter DC-link input terminals and three inverter output terminals.

Figure 2. Internal Block Diagram

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ABSOLUTE MAXIMUM RATINGS (T_J = 25°C, unless otherwise specified)

Symbol	Parameter	Conditions	Rating	Unit
INVERTER PART				
V _{PN}	Supply Voltage	Applied between P – N _U , N _V , N _W	450	V
V _{PN(Surge)}	Supply Voltage (Surge)	Applied between P – N _U , N _V , N _W	500	V
V _{CES}	Collector – Emitter Voltage		600	V
±I _C	Each IGBT Collector Current	T _C = 25°C, T _J < 150°C	15	A
±I _{CP}	Each IGBT Collector Current (Peak)	T _C = 25°C, T _J < 150°C, Under 1 ms Pulse Width (Note 4)	30	A
P _C	Collector Dissipation	T _C = 25°C per One Chip (Note 4)	38	W
T _J	Operating Junction Temperature		–40 ~ 150	°C

CONTROL PART

V _{DD}	Control Supply Voltage	Applied between V _{DD(H)} , V _{DD(L)} – COM	20	V
V _{BS}	High-Side Control Bias Voltage	Applied between V _{B(U)} – V _{S(U)} , V _{B(V)} – V _{S(V)} , V _{B(W)} – V _{S(W)}	20	V
V _{IN}	Input Signal Voltage	Applied between IN _(UH) , IN _(VH) , IN _(WH) , IN _(UL) , IN _(VL) , IN _(WL) – COM	–0.3 ~ V _{DD} + 0.3	V
V _{FO}	Fault Output Supply Voltage	Applied between V _{FO} – COM	–0.3 ~ V _{DD} + 0.3	V
I _{FO}	Fault Output Current	Sink Current at V _{FO} pin	1	mA
V _{SC}	Current-Sensing Input Voltage	Applied between C _{SC} – COM	–0.3 ~ V _{DD} + 0.3	V

BOOTSTRAP DIODE PART

V _{RRM}	Maximum Repetitive Reverse Voltage		600	V
I _F	Forward Current	T _C = 25°C, T _J < 150°C	0.5	A
I _{FP}	Forward Current (Peak)	T _C = 25°C, T _J < 150°C, Under 1 ms Pulse Width (Note 4)	2.0	A
T _J	Operating Junction Temperature		–40 ~ 150	°C

TOTAL SYSTEM

V _{PN(PROT)}	Self-Protection Supply Voltage Limit (Short-Circuit Protection Capability)	V _{DD} = V _{BS} = 13.5 ~ 16.5 V, T _J = 150°C, Non-Repetitive, < 2 μs	400	V
T _C	Module Case Operation Temperature	See Figure 1	–40 ~ 125	°C
T _{STG}	Storage Temperature		–40 ~ 125	°C
V _{ISO}	Isolation Voltage	60 Hz, Sinusoidal, AC 1 Minute, Connect Pins to Heat Sink Plate	2000	V _{rms}

THERMAL RESISTANCE

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
R _{th(j-c)Q}	Junction to Case Thermal Resistance (Note 5)	Inverter IGBT Part (per 1 / 6 Module)	–	–	3.20	°C/W
R _{th(j-c)F}		Inverter FWDi Part (per 1 / 6 Module)	–	–	4.00	°C/W

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

4. These values had been made an acquisition by the calculation considered to design factor.

5. For the measurement point of case temperature (T_C), please refer to Figure 1.

ELECTRICAL CHARACTERISTICS ($T_J = 25^\circ\text{C}$, unless otherwise specified)

Symbol		Parameter	Conditions	Min.	Typ.	Max.	Unit	
INVERTER PART								
V _{CE(SAT)}		Collector – Emitter Saturation Voltage	V _{DD} = V _{BS} = 15 V V _{IN} = 5 V	I _C = 15 A, T _J = 25°C	–	1.60	2.20	V
V _F		FWDi Forward Voltage	V _{IN} = 0 V	I _F = 15 A, T _J = 25°C	–	2.00	2.60	V
HS	t _{ON}	Switching Times	V _{PN} = 300 V, V _{DD} = V _{BS} = 15 V, I _C = 15 A T _J = 25°C V _{IN} = 0 V ↔ 5 V, Inductive Load (Note 6)		0.40	0.80	1.30	μs
	t _{C(ON)}				–	0.20	0.50	μs
	t _{OFF}				–	0.85	1.35	μs
	t _{C(OFF)}				–	0.25	0.55	μs
	t _{rr}				–	0.10	–	μs
LS	t _{ON}		V _{PN} = 300 V, V _{DD} = V _{BS} = 15 V, I _C = 15 A T _J = 25°C V _{IN} = 0 V ↔ 5 V, Inductive Load (Note 6)		0.45	0.85	1.35	μs
	t _{C(ON)}				–	0.25	0.55	μs
	t _{OFF}				–	0.90	1.40	μs
	t _{C(OFF)}				–	0.25	0.55	μs
	t _{rr}				–	0.15	–	μs
I _{CES}		Collector – Emitter Leakage Current	V _{CE} = V _{CES}		–	–	1	mA

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

6. t_{ON} and t_{OFF} include the propagation delay of the internal drive IC. $t_{C(ON)}$ and $t_{C(OFF)}$ are the switching times of IGBT under the given gate driving condition internally. For the detailed information, please see Figure 3.

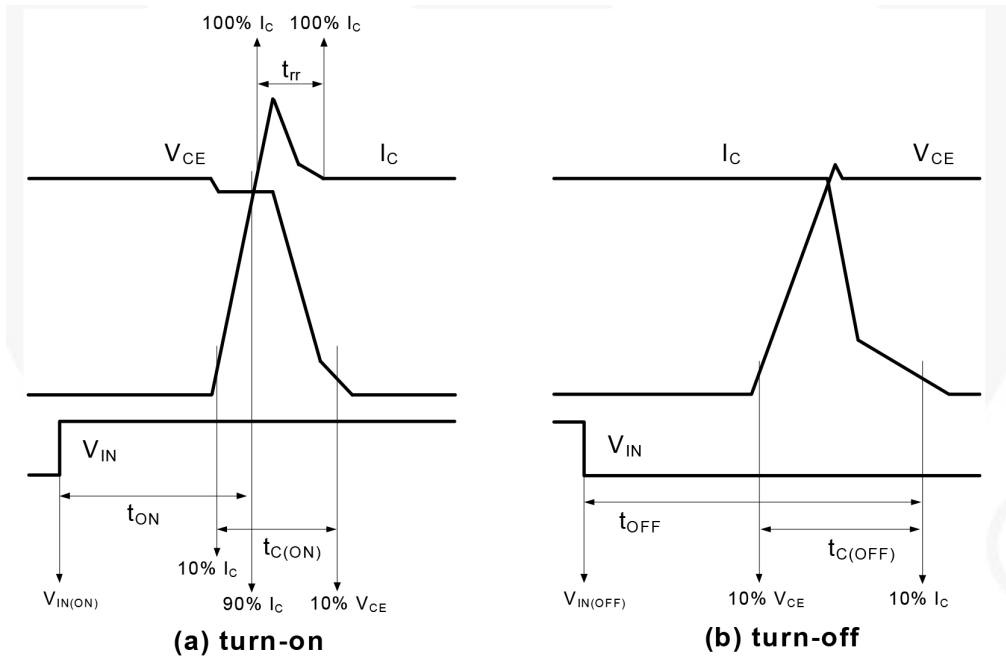


Figure 3. Switching Time Definition

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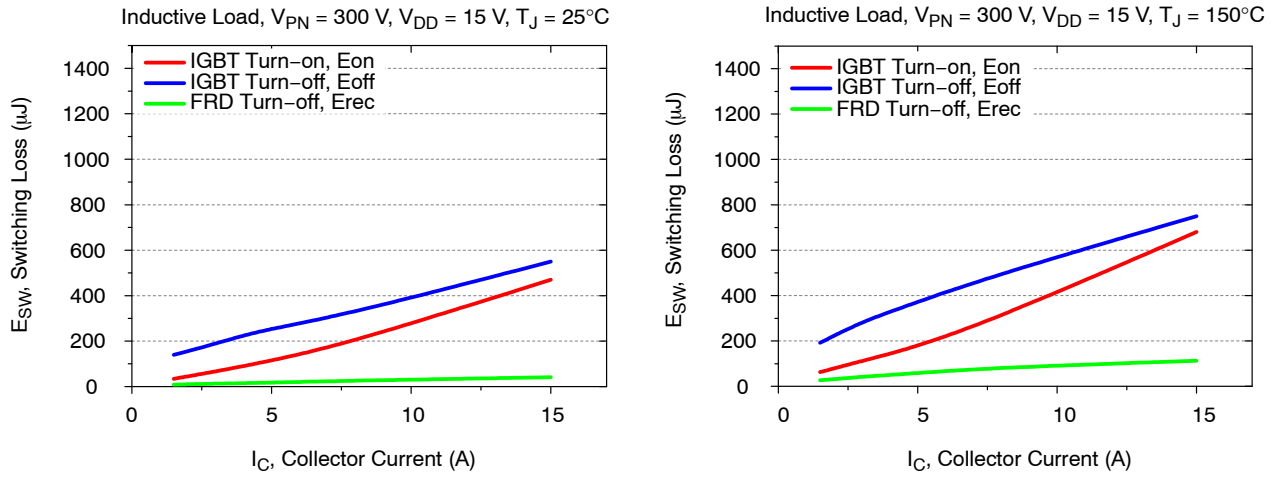


Figure 4. Switching Loss Characteristics (Typical)

CONTROL PART

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
I_{QDDH}	Quiescent V_{DD} Supply Current	$V_{DD(H)} = 15\text{ V}$, $I_{N(UH, VH, WH)} = 0\text{ V}$	$V_{DD(H)} - \text{COM}$	–	–	0.10 mA
I_{QDDL}		$V_{DD(L)} = 15\text{ V}$, $I_{N(UL, VL, WL)} = 0\text{ V}$	$V_{DD(L)} - \text{COM}$	–	–	2.65 mA
I_{PDDH}	Operating V_{DD} Supply Current	$V_{DD(H)} = 15\text{ V}$, $f_{PWM} = 20\text{ kHz}$, Duty = 50%, Applied to one PWM Signal Input for High-Side	$V_{DD(H)} - \text{COM}$	–	–	0.15 mA
I_{PDDL}		$V_{DD(L)} = 15\text{ V}$, $f_{PWM} = 20\text{ kHz}$, Duty = 50%, Applied to one PWM Signal Input for Low-Side	$V_{DD(L)} - \text{COM}$	–	–	4.00 mA
I_{QBS}	Quiescent V_{BS} Supply Current	$V_{BS} = 15\text{ V}$, $I_{N(UH, VH, WH)} = 0\text{ V}$	$V_{B(U)} - V_{S(U)}$, $V_{B(V)} - V_{S(V)}$, $V_{B(W)} - V_{S(W)}$	–	–	0.30 mA
I_{PBS}	Operating V_{BS} Supply Current	$V_{DD} = V_{BS} = 15\text{ V}$, $f_{PWM} = 20\text{ kHz}$, Duty = 50%, Applied to one PWM Signal Input for High-Side	$V_{B(U)} - V_{S(U)}$, $V_{B(V)} - V_{S(V)}$, $V_{B(W)} - V_{S(W)}$	–	–	2.00 mA
V_{FOH}	Fault Output Voltage	$V_{SC} = 0\text{ V}$, V_{FO} Circuit: 4.7 k Ω to 5 V Pull-up	4.5	–	–	V
V_{FOL}		$V_{SC} = 1\text{ V}$, V_{FO} Circuit: 4.7 k Ω to 5 V Pull-up	–	–	0.5	V
$V_{SC(ref)}$	Short Circuit Trip Level	$V_{DD} = 15\text{ V}$ (Note 7)	$C_{SC} - \text{COM}$	0.45	0.50	0.55 V
UV_{DDD}	Supply Circuit Under-Voltage Protection	Detection Level	10.5	–	13.0	V
UV_{DDR}		Reset Level	11.0	–	13.5	V
UV_{BSD}		Detection Level	10.0	–	12.5	V
UV_{BSR}		Reset Level	10.5	–	13.0	V
t_{FOD}	Fault-Out Pulse Width		30	–	–	μs
$V_{IN(ON)}$	ON Threshold Voltage	Applied between $I_{N(UH, VH, WH)} - \text{COM}$, $I_{N(UL, VL, WL)} - \text{COM}$	–	–	2.6	V
$V_{IN(OFF)}$	OFF Threshold Voltage		0.8	–	–	V
R_{TH}	Resistance of Thermistor	at $T_{TH} = 25^\circ\text{C}$ (Note 8)	–	47	–	k Ω
		at $T_{TH} = 100^\circ\text{C}$	–	2.9	–	k Ω

7. Short-circuit current protection is functioning only at the low-sides.

8. T_{TH} is the temperature of thermistor itself. To know case temperature (T_C), please make the experiment considering your application.

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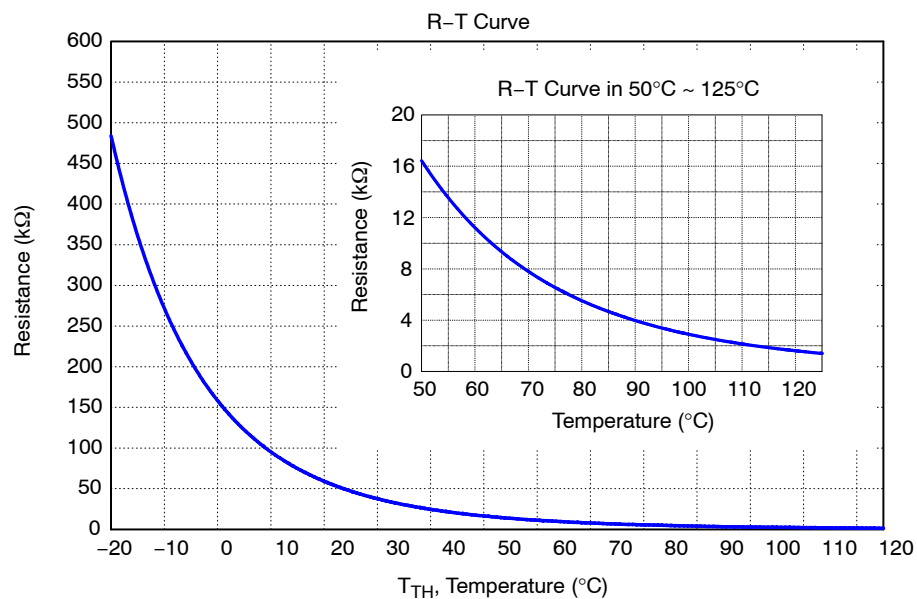
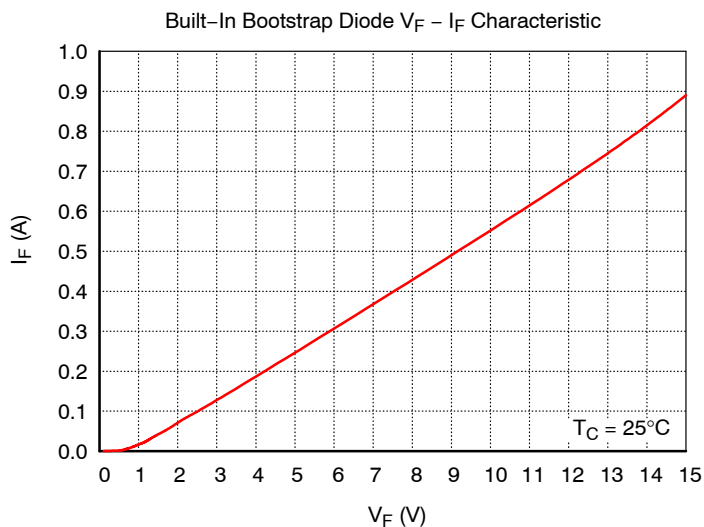


Figure 5. R-T Curve of The Built-In Thermistor

BOOTSTRAP DIODE PART

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Unit
V_F	Forward Voltage	$I_F = 0.1 \text{ A}$, $T_C = 25^\circ\text{C}$	–	2.5	–	V
t_{rr}	Reverse-Recovery Time	$I_F = 0.1 \text{ A}$, $dI_F / dt = 50 \text{ A} / \mu\text{s}$, $T_J = 25^\circ\text{C}$	–	80	–	ns



NOTE: Built-in bootstrap diode includes around 15Ω resistance characteristic.

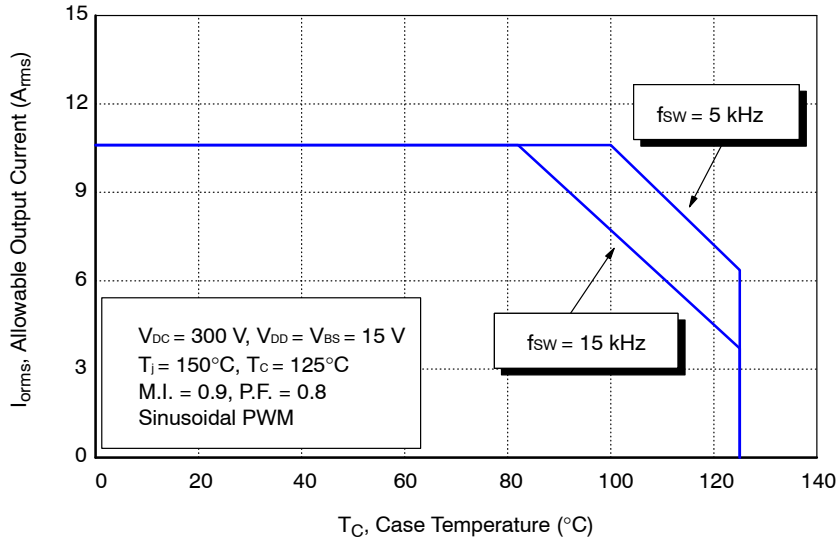
Figure 6. Built-In Bootstrap Diode Characteristic

RECOMMENDED OPERATING CONDITIONS

Symbol	Parameter	Conditions	Value			Unit
			Min.	Typ.	Max.	
V_{PN}	Supply Voltage	Applied between P – N_U , N_V , N_W	–	300	400	V
V_{DD}	Control Supply Voltage	Applied between $V_{DD(H)}$, $V_{DD(L)}$ – COM	13.5	15.0	16.5	V
V_{BS}	High-Side Bias Voltage	Applied between $V_{B(U)} - V_{S(U)}$, $V_{B(V)} - V_{S(V)}$, $V_{B(W)} - V_{S(W)}$	13.0	15.0	18.5	V
dV_{DD} / dt , dV_{BS} / dt	Control Supply Variation		–1	–	1	V / μ s
t_{dead}	Blanking Time for Preventing Arm – Short	For each input signal	1	–	–	μ s
f_{PWM}	PWM Input Signal	$-40^{\circ}\text{C} \leq T_C \leq 125^{\circ}\text{C}$, $-40^{\circ}\text{C} \leq T_J \leq 150^{\circ}\text{C}$	–	–	20	kHz
V_{SEN}	Voltage for Current Sensing	Applied between N_U , N_V , N_W – COM (Including Surge-Voltage)	–4	–	4	V
$PW_{IN(ON)}$	Minimum Input Pulse Width	$V_{DD} = V_{BS} = 15\text{ V}$, $I_C \leq 15\text{ A}$, Wiring Inductance between N_U , v, w and DC Link N < 10 nH (Note 9)	0.5	–	–	μ s
$PW_{IN(OFF)}$			0.5	–	–	
$PW_{IN(ON)}$	Minimum Input Pulse Width	$V_{DD} = V_{BS} = 15\text{ V}$, $I_C \leq 30\text{ A}$, Wiring Inductance between N_U , v, w and DC Link N < 10 nH (Note 9)	1.2	–	–	μ s
$PW_{IN(OFF)}$			1.2	–	–	
T_J	Junction Temperature		–40	–	150	$^{\circ}\text{C}$

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

9. This product might not make right output response if input pulse width is less than the recommended value.



NOTE: This allowable output current value is the reference data for the safe operation of this product. This may be different from the actual application and operating condition.

Figure 7. Allowable Maximum Output Current

MECHANICAL CHARACTERISTICS AND RATINGS

Parameter	Conditions		Min.	Typ.	Max.	Unit
Device Flatness	See Figure 8		0	–	+120	μm
Mounting Torque	Mounting Screw: M3 See Figure 9	Recommended 0.7 N/m	0.6	0.7	0.8	N/m
		Recommended 7.1 kg/cm	6.2	7.1	8.1	kg/cm
Weight			–	11.00	–	g

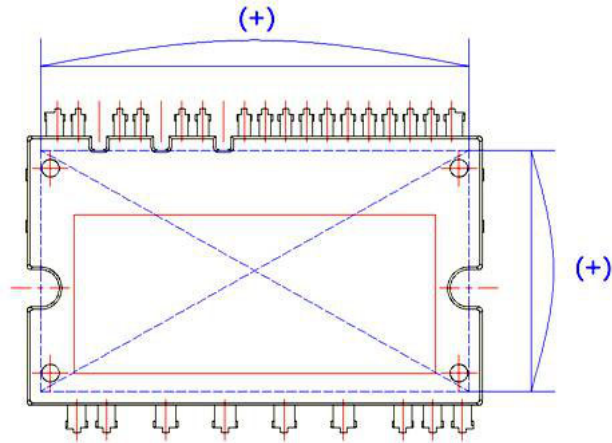


Figure 8. Flatness Measurement Position

Pre - Screwing : 1→2

Final Screwing : 2→1

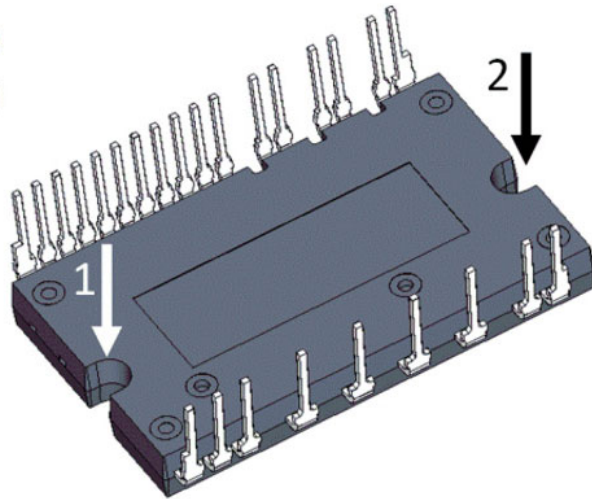
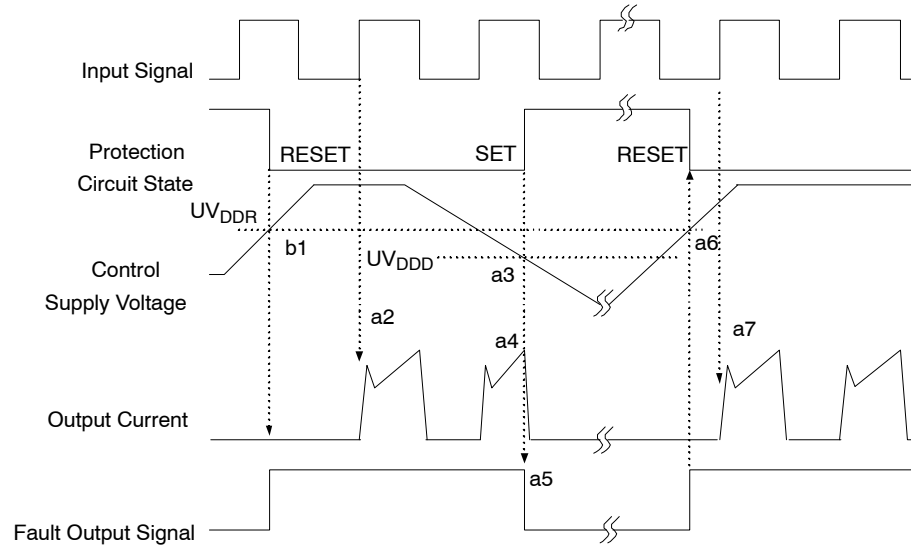


Figure 9. Mounting Screws Torque Order

NOTES:

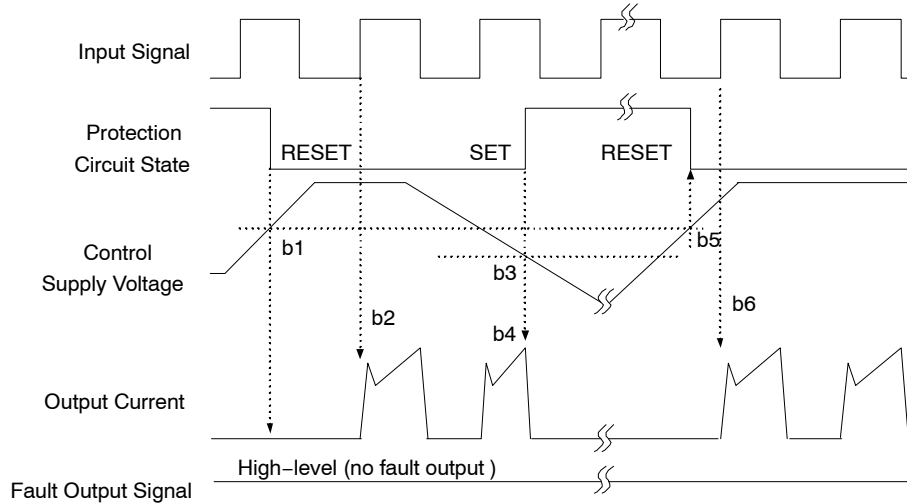
10. Do not make over torque when mounting screws. Much mounting torque may cause ceramic cracks, as well as bolts and Al heat-sink destruction.
11. Avoid one-sided tightening stress. Figure 9 shows the recommended torque order for the mounting screws. Uneven mounting can cause the ceramic substrate damaged. The pre-screwing torque is set to 20 ~ 30% of maximum torque rating.

Time Charts of Protective Function



- a1 : Control supply voltage rises: after the voltage rises UV_{DDR} , the circuits start to operate when the next input is applied.
a2 : Normal operation: IGBT ON and carrying current.
a3 : Under-voltage detection (UV_{DD}).
a4 : IGBT OFF in spite of control input condition.
a5 : Fault output operation starts with a fixed pulse width.
a6 : Under-voltage reset (UV_{DDR}).
a7 : Normal operation: IGBT ON and carrying current by triggering next signal from LOW to HIGH.

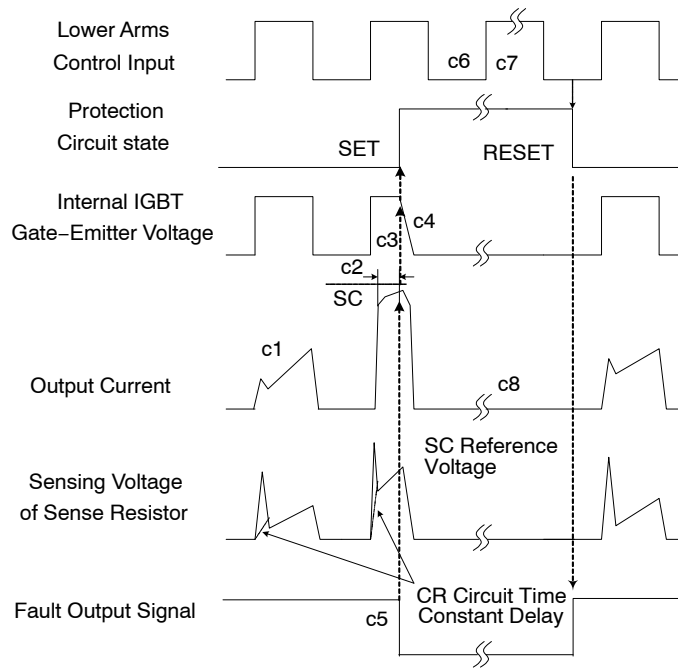
Figure 10. Under-Voltage Protection (Low-Side)



- b1 : Control supply voltage rises: after the voltage reaches UV_{BSR} , the circuits start to operate when the next input is applied.
b2 : Normal operation: IGBT ON and carrying current.
b3 : Under-voltage detection (UV_{BS}).
b4 : IGBT OFF in spite of control input condition, but there is no fault output signal.
b5 : Under-voltage reset (UV_{BSR}).
b6 : Normal operation: IGBT ON and carrying current by triggering next signal from LOW to HIGH.

Figure 11. Under-Voltage Protection (High-Side)

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(with the external sense resistance and RC filter connection)

c1 : Normal operation: IGBT ON and carrying current.

c2 : Short-circuit current detection (SC trigger).

c3 : All low-side IGBTs gate are hard interrupted.

c4 : All low-side IGBTs turn OFF.

c5 : Fault output operation starts with a fixed pulse width according to the condition of the external capacitor CFOD.

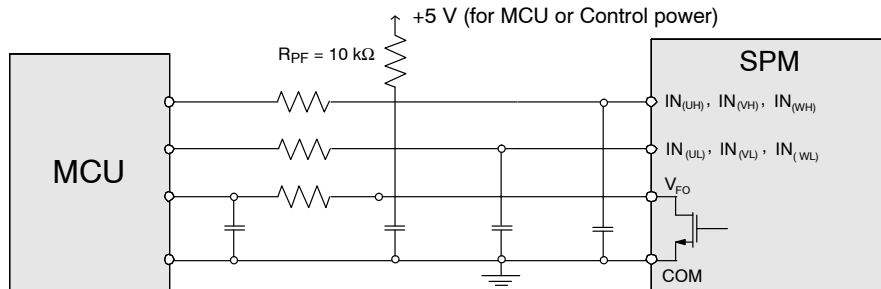
c6 : Input HIGH: IGBT ON state, but during the active period of fault output, the IGBT doesn't turn ON.

c7 : Fault output operation finishes, but IGBT doesn't turn on until triggering the next signal from LOW to HIGH.

c8 : Normal operation: IGBT ON and carrying current.

Figure 12. Short-Circuit Current Protection (Low-Side Operation only)

Input/Output Interface Circuit



NOTE: RC coupling at each input might change depending on the PWM control scheme used in the application and the wiring impedance of the application's printed circuit board. The input signal section of the Motion SPM 45 product integrates 5 kΩ (typ.) pull-down resistor. Therefore, when using an external filtering resistor, please pay attention to the signal voltage drop at input terminal.

Figure 13. Recommended MCU I/O Interface Circuit

The diagram illustrates the internal architecture of a 1000W 3-Phase Inverter, centered around an MCU (Microcontroller Unit) and two specialized ICs: the HVIC (High Voltage Integrated Circuit) and the LVIC (Low Voltage Integrated Circuit).

MCU (Microcontroller Unit): The MCU is the central control unit, connected to various components via its pins. It interfaces with the HVIC and LVIC through pins labeled Gating UH, Gating VH, Gating WH, Gating UL, Gating VL, Gating WL, Fault, and Input Signal for Short-Circuit Protection. It also manages power supply regulation through pins connected to +15V and +5V regulators.

HVIC (High Voltage Integrated Circuit): The HVIC is responsible for high-voltage switching. It includes pins for V_{B(U)}, V_{B(V)}, V_{B(W)}, V_{DD}, and COM. It also features pins for V_{S(U)}, V_{S(V)}, V_{S(W)}, and V_{DS(U)}. The HVIC is connected to the motor (M) and the three-phase load (N_U, N_V, N_W) through its output pins.

LVIC (Low Voltage Integrated Circuit): The LVIC is responsible for low-voltage switching. It includes pins for V_{DD}, V_{FO}, IN(U/L), IN(V/L), IN(W/L), COM, and CSC. It also features pins for OUT(U/L), OUT(V/L), and OUT(W/L). The LVIC is connected to the motor (M) and the three-phase load (N_U, N_V, N_W) through its output pins.

Power Supply and Regulation: The system is powered by a +15V regulator and a +5V regulator. The +15V regulator is connected to the MCU and the HVIC. The +5V regulator is connected to the MCU and the LVIC. The regulators are connected to the MCU and the HVIC/LVIC through various pins.

Output and Load: The inverter output is connected to a motor (M) and a three-phase load (N_U, N_V, N_W). The load is connected to the motor through resistors R_{SU}, R_{SV}, and R_{SW}. The motor is connected to the load through its terminals U, V, and W.

Fault Detection and Monitoring: The system includes a fault detection section with a fault pin and a fault signal output. It also includes a temperature monitoring section with a thermistor (R_{TH}) and a temperature monitoring pin.

Input and Gating: The system includes an input section with three-phase input (U, V, W) and a gating section with three-phase gating (UH, VH, WH, UL, VL, WL). The input and gating signals are connected to the MCU and the HVIC/LVIC through various pins.

NOTES:

- 13

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PACKAGE MARKING AND ORDERING INFORMATION

Device	Device Marking	Package	Shipping
FNA41560T2	FNA41560T2	SPMAA-C26 / 26LD, PDD STD CERAMIC TYPE, LONG LEAD DUAL FORM TYPE (Pb-Free)	12 Units / Rail

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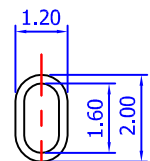
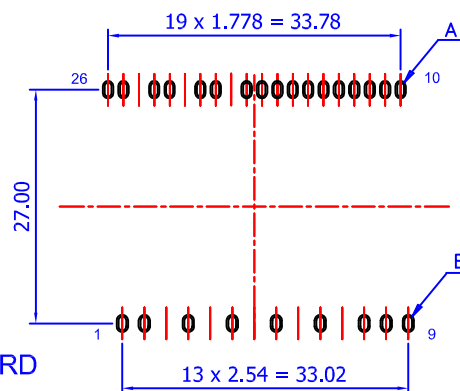
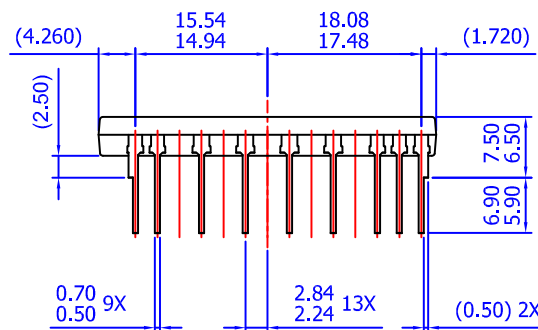
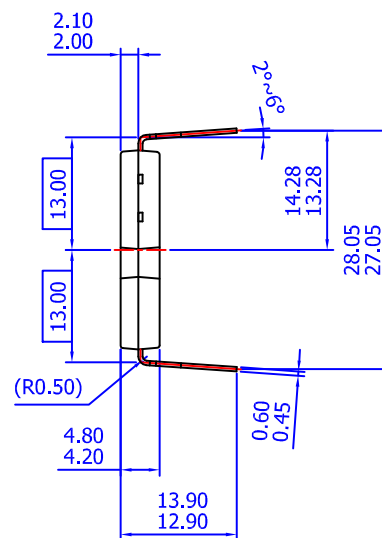
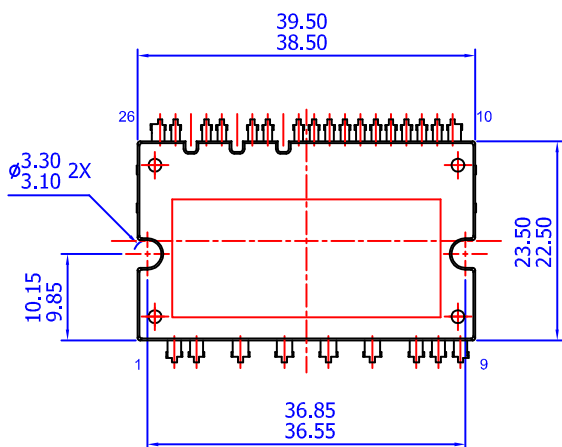
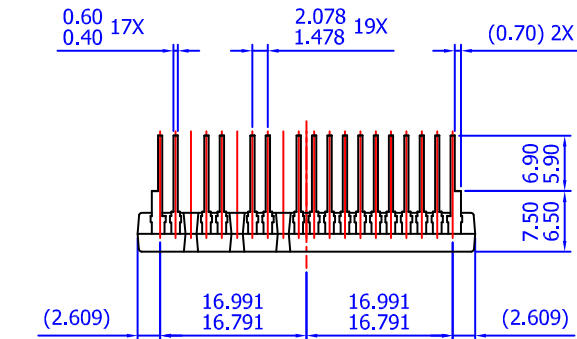
MECHANICAL CASE OUTLINE PACKAGE DIMENSIONS

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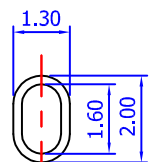
ON

SPMAA-C26 / 26LD, PDD STD CERAMIC TYPE, LONG LEAD DUAL FORM TYPE CASE MODFC ISSUE O

DATE 31 JAN 2017



DETAIL A
(SCALE N/A)



DETAIL B
(SCALE N/A)

- NOTES: UNLESS OTHERWISE SPECIFIED
- A) THIS PACKAGE DOES NOT COMPLY TO ANY CURRENT PACKAGING STANDARD
 - B) ALL DIMENSIONS ARE IN MILLIMETERS
 - C) DIMENSIONS ARE EXCLUSIVE OF BURRS, MOLD FLASH, AND TIE BAR EXTRUSIONS
 - D) () IS REFERENCE

LAND PATTERN RECOMMENDATIONS

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DESCRIPTION:	SPMAA-C26 / 26LD, PDD STD CERAMIC TYPE, LONG LEAD DUAL	PAGE 1 OF 1

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