

TPS7H2201-SP 和 TPS7H2201-SEP 耐辐射 1.5V 至 7V、6A 电子保险丝

1 特性

- 提供标准微型电路，[SMD 5962R17220](#)
- 提供供应商项目图，[VID V62/23608](#)
- 辐射性能：
 - 耐辐射保障 (RHA) 高达 TID 100krad(Si)
 - 单粒子锁定 (SEL)、单粒子烧毁 (SEB) 和单粒子栅穿 (SEGR) 对于 LET 的抗扰度 = 75MeV-cm²/mg
 - SEFI/SET 对于 LET 的额定抗扰度 = 75MeV-cm²/mg
- 集成式单通道电子保险丝
- 输入电压范围：1.5V 至 7V
- 低导通电阻 (R_{ON})：
 - 对于 CFP 和 KGD 封装，在 25°C 且 V_{IN} = 5V 时的最大值为 35mΩ
 - 对于 HTSSOP 封装，在 25°C 且 V_{IN} = 5V 时的最大值为 23mΩ
- 6A 最大持续开关电流
- 低控制输入阈值支持使用 1.2V、1.8V、2.5V 和 3.3V 逻辑电平
- 可配置上升时间 (软启动)
- 反向电流保护
- 可编程和内部电流限制 (快速跳变)
- 可编程故障计时器 (电流限制和重试模式)
- 热关断
- 带散热焊盘的陶瓷和塑料封装

2 应用

- 航天卫星电源管理和配电
- 耐辐射和抗辐射电源树应用
- 支持军用 (- 55°C 至 125°C) 温度范围

3 说明

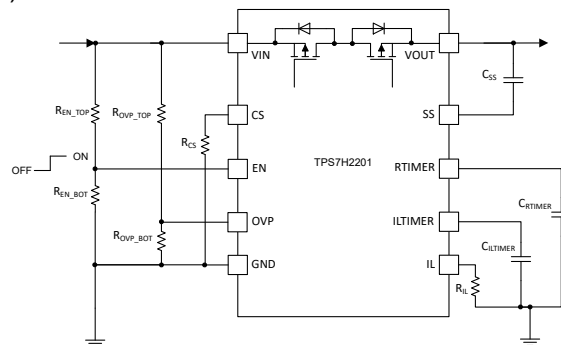
TPS7H2201 是一款单通道电子保险丝，可提供用于更大限度地降低浪涌电流的可配置上升时间和反向电流保护。该器件包含一个可在 1.5V 至 7V 输入电压范围内运行的 P 沟道 MOSFET，并且支持 6A 的最大持续电流。开关由可与低压控制信号直接连接的打开和关闭输入 (EN) 控制。

TPS7H2201 采用具有集成散热焊盘的陶瓷和塑料封装，可支持高功率耗散。该器件在自然通风环境下的额定运行温度范围为 - 55°C 至 125°C。

器件信息

器件型号 ⁽¹⁾	等级	封装
5962R1722001VXC	飞行等级 RHA 100krad (Si)	16 引脚 CDFP 11.00 × 9.60mm 重量：1.56g ⁽³⁾
5962-1722001VXC	飞行等级 QMLV	
TPS7H2201HKR/EM	工程样片 ⁽²⁾	
TPS7H2201MDAPTSEP	9 月	32 引脚 HTSSOP 6.10 × 11.00mm 重量：0.191g ⁽³⁾
TPS7H2201EVM-CVAL	陶瓷评估板	EVM

- 如需了解所有可用封装，请参阅数据表末尾的可订购产品附录。另请参阅[器件选项](#)。
- 这些器件仅适用于工程评估。器件按照不合规的流程进行加工处理。这些器件不适用于鉴定、量产、辐射测试或飞行。也不保证这些器件在 MIL 规定的 - 55°C 至 125°C 完整温度范围内或运行寿命中的性能。
- 尺寸和质量值为标称值。



简化原理图



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4 Device Options

GENERIC PART NUMBER	RADIATION RATING ⁽¹⁾	GRADE ⁽²⁾	PACKAGE	ORDERABLE PART NUMBER
TPS7H2201-SP	TID of 100 krad(Si) RLAT, DSEE free to 75 MeV-cm ² /mg	QMLV-RHA	16-pin HKR CFP	5962R1722001VXC
		QMLP-RHA	32-pin DAP HTSSOP	5962R1722002PYE
		KGD (QMLV-RHA)	Die	5962R1722001V9A
	None	Engineering Model ⁽³⁾	16-pin HKR CFP	PTS7H2201HKR/EM
			Die	TPS7H2201Y/EM
TPS7H2201-SEP	TID of 50 krad(Si) RLAT, DSEE free to 43 MeV-cm ² /mg	Space Enhanced Plastic	32-pin DAP HTSSOP	TPS7H2201MDAPTSEP

- (1) TID is total ionizing dose and DSEE is destructive single event effects. Additional information is available in the associated TID reports and SEE reports for each product.
- (2) For additional information about part grade, view [SLYB235](#).
- (3) These units are intended for engineering evaluation only. They are processed to a non-compliant flow (such as no burn-in and only 25°C testing). These units are not suitable for qualification, production, radiation testing, or flight use. Parts are not warranted as to performance over temperature or operating life.

5 Pin Configuration and Functions

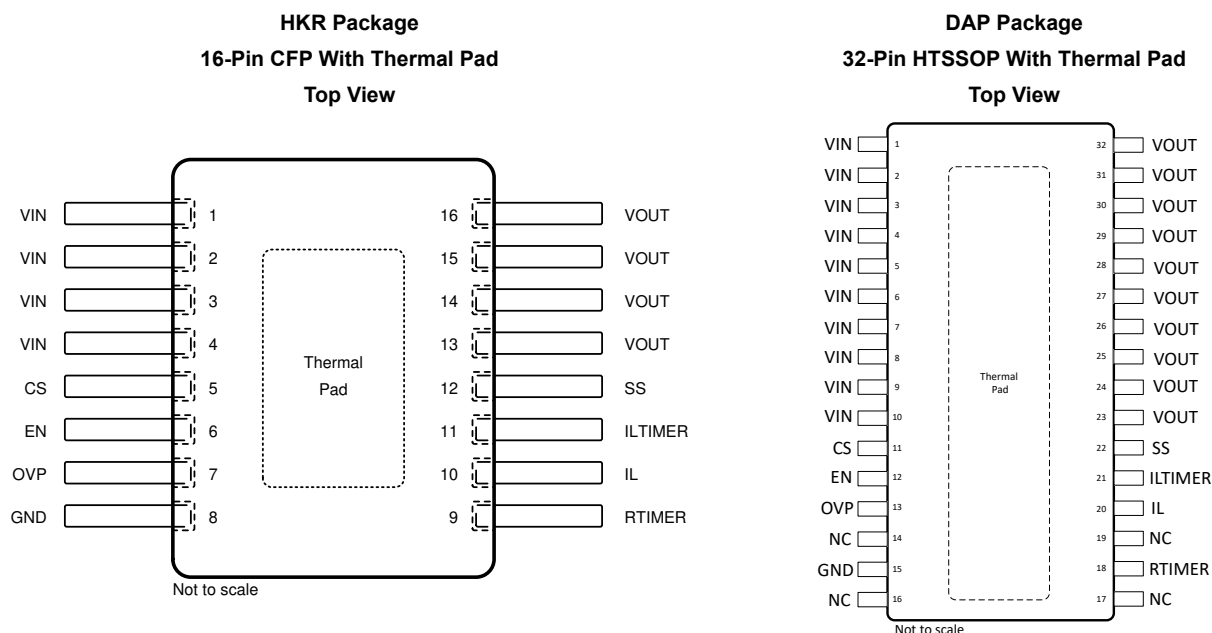


表 5-1. Pin Functions

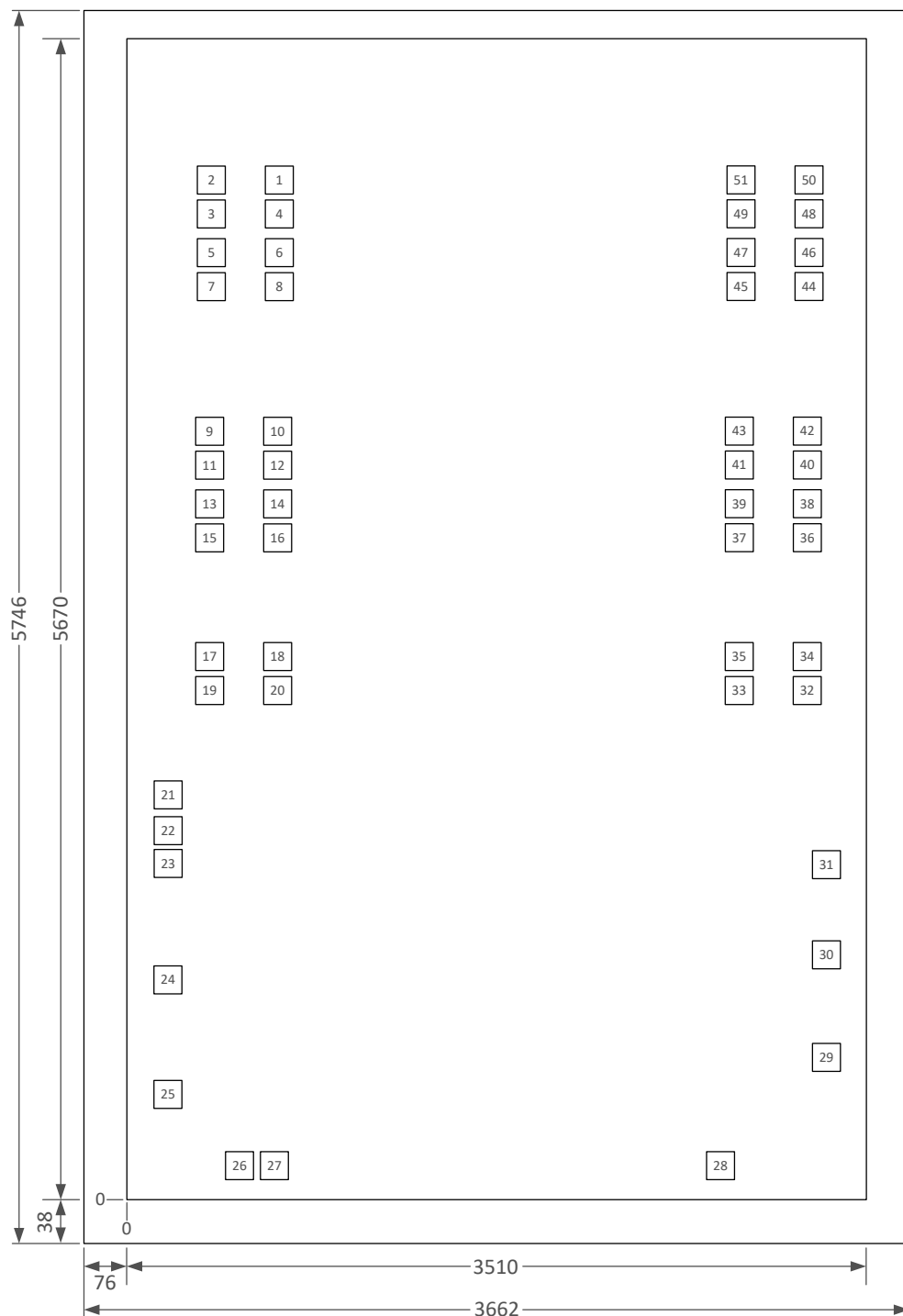
PIN			I/O ⁽¹⁾	DESCRIPTION
	HKR (16) NO.	PW (32) NO.	NAME	
1-4	1-10	VIN	I	Switch input. Input bypass capacitor recommended for minimizing V_{IN} dip.
5	11	CS	O	Current sense pin proportional to output current. Connect a resistor to GND.
6	12	EN	I	Active high switch control input. Do not leave floating.
7	13	OVP	I	Overvoltage protection. Programmable using an external resistor divider. If no OVP is desired, this pin should be connected to GND.
8	15	GND	—	Device ground. ⁽²⁾
9	18	RTIMER	I/O	Capacitor programmed fault timer control during disabled and retry mode. Connecting this pin to GND holds the switch disabled until the EN pin is cycled. Do not float this pin or connect it to VIN.
10	20	IL	I/O	Current limiter control. Programmable using an external resistor to GND. Do not float this pin.
11	21	ILTIMER	I	Capacitor programmed fault timer control during current limiting mode. Connecting this pin to VIN uses the internal current limit timer and connecting this pin to GND disables the internal timer functionality for the ILTIMER as well as retry mode. In this case, the device will remain at programmed current limit indefinitely in the event of a short without going into retry mode. Do not float this pin.
12	22	SS	I/O	Switch slew rate control. See the § 8.3.2 section for more information.
13-16	23-32	VOUT	O	Switch output. A minimum 10- μ F output capacitor is recommended.
	14,16,17,19	NC	—	No connect. This pin is not internally connected. It is recommended to connect these pins to GND to prevent charge buildup; however, these pins can also be left open or tied to any voltage between GND and VIN.
	—	Thermal Pad	—	Thermal pad (exposed center pad) for heat dissipation purposes. Thermal pad is internally connected to seal ring and GND.

(1) I = Input, O = Output, I/O = Input or Output, — = Other

(2) Thermal pad is internally connected to the seal ring and GND for HKR option.

表 5-2. Bare Die Information

DIE THICKNESS	BACKSIDE FINISH	BACKSIDE POTENTIAL	BOND PAD METALLIZATION COMPOSITION	BOND PAD THICKNESS
15 mils	Silicon with backgrind	Ground	ALCU	1050 nm



1. All dimensions in microns (μm).
2. The inner rectangle is the die and the outer rectangle is the die plus scribe lines.

表 5-3. Bond Pad Coordinates in Microns

DESCRIPTION	PAD NUMBER	X MIN	Y MIN	X MAX	Y MAX
VIN	1	611.78	4976.1	751.73	5116.05
VIN	2	258.17	4976.1	398.12	5116.05
VIN	3	258.17	4809.15	398.12	4949.1
VIN	4	611.78	4809.15	751.73	4949.1
VIN	5	258.17	4641.39	398.12	4781.34
VIN	6	611.78	4641.39	751.73	4781.34
VIN	7	258.17	4473.59	398.12	4613.54
VIN	8	611.78	4473.59	751.73	4613.54
VIN	9	258.17	3647.7	398.12	3787.65
VIN	10	611.78	3647.7	751.73	3787.65
VIN	11	258.17	3480.75	398.12	3620.7
VIN	12	611.78	3480.75	751.73	3620.7
VIN	13	258.17	3312.99	398.12	3452.94
VIN	14	611.78	3312.99	751.73	3452.94
VIN	15	258.17	3145.19	398.12	3285.14
VIN	16	611.78	3145.19	751.73	3285.14
VIN	17	258.17	2315.57	398.12	2455.52
VIN	18	611.78	2315.57	751.73	2455.52
VIN	19	258.17	2146.37	398.12	2286.32
VIN	20	611.78	2146.37	751.73	2286.36
AVDD	21	54.99	1842.03	194.94	1981.98
AVDD	22	54.99	1671.48	194.94	1811.43
CS	23	54.99	1480.77	194.94	1620.72
EN	24	54.99	972.68	194.94	1112.63
OVP	25	54.99	406.26	194.94	546.21
GND	26	407.21	54.99	547.16	194.94
GND	27	577.76	54.99	717.71	194.94
RTIMER	28	2792.88	54.99	2932.83	194.94
IL	29	3315.06	587.43	3455.01	727.38
ILTIMER	30	3315.06	1099.26	3455.01	1239.21
SS	31	3315.06	1544.09	3455.01	1684.04
VOUT	32	3111.66	2146.37	3251.61	2286.32
VOUT	33	2758.05	2146.37	2898	2286.32
VOUT	34	3111.66	2315.57	3251.61	2455.52
VOUT	35	2758.05	2315.57	2898	2455.52
VOUT	36	3111.66	3145.19	3251.61	3285.14
VOUT	37	2758.05	3145.19	2898	3285.14
VOUT	38	3111.66	3312.99	3251.61	3452.94
VOUT	39	2758.05	3312.99	2898	3452.94
VOUT	40	3111.66	3480.75	3251.61	3620.7
VOUT	41	2758.05	3480.75	2898	3620.7
VOUT	42	3111.66	3647.7	3251.61	3787.65
VOUT	43	2758.05	3647.7	2898	3787.65
VOUT	44	3111.66	4473.59	3251.61	4613.54
VOUT	45	2758.05	4473.59	2898	4613.54

表 5-3. Bond Pad Coordinates in Microns (续)

DESCRIPTION	PAD NUMBER	X MIN	Y MIN	X MAX	Y MAX
VOUT	46	3111.66	4641.39	3251.61	4781.34
VOUT	47	2758.05	4641.39	2898	4781.34
VOUT	48	3111.66	4809.15	3251.61	4949.1
VOUT	49	2758.05	4809.15	2898	4949.1
VOUT	50	3111.66	4976.1	3251.61	5116.05
VOUT	51	2758.05	4976.1	2898	5116.05

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)^{(1) (2)}

		MIN	MAX	UNIT
V _{IN}	Input voltage	– 0.3	7.5	V
V _{OUT}	Output voltage	– 0.3	7.5	V
EN, OVP	Enable and over voltage protection pins	– 0.3	7.5	V
CS, ILTMR, RTMR, IL, SS	Current sense, current limit timer, retry timer, current limit and soft start pins	– 0.3	V _{IN} + 0.3	V
I _{MAX}	Maximum continuous switch current		9	A
I _{PLS}	Maximum pulsed switch current (t ≤ 5μs)		45	A
T _J	Maximum junction temperature	– 55	150	°C
T _{stg}	Storage temperature	– 65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values are with respect to network ground pin.

6.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±4000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾	±750	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 500-V HBM is possible with the necessary precautions.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 250-V CDM is possible with the necessary precautions.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
V _{IN}	Input voltage	1.5	7	V
SR _{VIN}	Input voltage slew rate		0.01	V/μs
V _{OUT}	Output voltage	0	7 ⁽¹⁾	V
I _{MAX}	Maximum continuous switch current		6	A
T _J	Operating junction temperature ⁽²⁾	– 55	125	°C

- (1) This maximum V_{OUT} voltage is only applicable when the device is disabled (EN = Low). When the device is enabled (EN = High), the maximum V_{OUT} voltage is the input voltage, V_{IN}.
- (2) In applications where high power dissipation and/or poor package thermal resistance is present, the maximum ambient temperature may have to be derated. Maximum ambient temperature [T_{A(max)}] is dependent on the maximum operating junction temperature [T_{J(max)}], the maximum power dissipation of the device in the application [P_{D(max)}], and the junction-to-ambient thermal resistance of the part/package in the application (θ_{JA}), as given by the equation: T_{A(max)} = T_{J(max)} – (θ_{JA} × P_{D(max)}).

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPS7H2201-SP	TPS7H2201-SEP	UNIT
		HKR (CFP)	DAP (HTSSOP)	
		16 PINS	32 PINS	
R _{θJA}	Junction-to-ambient thermal resistance	72.3	23.5	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	96.1	11.2	
R _{θJB}	Junction-to-board thermal resistance	42.1	5.4	
ψ _{JT}	Junction-to-top characterization parameter	3.3	0.1	
ψ _{JB}	Junction-to-board characterization parameter	42.5	5.4	
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	0.6	0.5	

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

6.5 Electrical Characteristics: All Devices

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS		SUBGROUP (1)	MIN	TYP	MAX	UNIT
POWER SUPPLIES AND CURRENTS								
V _{INHUVLO}	Internal VIN UVLO voltage, rising					1.32		V
V _{INLUVLO}	Internal VIN UVLO voltage, falling					1.23		V
HYST _{VIN-UVLO}	Internal VIN UVLO hysteresis					92		mV
I _Q	Quiescent current	I _{OUT} = 0 mA, V _{IN} = EN = 5 V, CS resistor of 20 kΩ to GND		1, 2, 3		2.4	6.5	mA
I _F	VIN to VOUT forward leakage current	EN = VOUT = GND, measured VOUT current	1.5 V ≤ VIN ≤ 7 V	1, 2, 3			250	μA
			VIN = 1.5 V	1, 2, 3		3.27		
			VIN = 1.8 V	1, 2, 3		3.35		
			VIN = 3.3 V	1, 2, 3		3.62		
			VIN = 5 V	1, 2, 3		4.11		
			VIN = 7 V	1, 2, 3		6.82		
I _{SD VIN}	VIN off-state supply current	EN = GND, I _{OUT} = 0 mA, measured VIN current	VIN = 5 V	1, 2, 3		0.4	3	mA
			VIN = 3.3 V	1, 2, 3		0.3	3	
			VIN = 1.8 V	1, 2, 3		0.2	3	
			After TID = 100 krad, VIN = 1.8, 3.3, and 5 V	1			3.1	
SOFT START								
I _{SS}	Soft start charge current	1 V on SS pin		1, 2, 3		65	83	μA
SR _{SS}	Soft start slew rate	SS pin floating, COUT = 10 μF				295		mV/μs
ENABLE AND UNDERVOLTAGE LOCKOUT (EN/UVLO) INPUT								
V _{IHEN}	EN/UVLO threshold voltage, rising			1, 2, 3	0.56	0.61	0.65	V
V _{ILEN}	EN/UVLO threshold voltage, falling			1, 2, 3	0.47	0.51	0.55	V
HYST _{EN}	EN/UVLO hysteresis voltage			1, 2, 3		93	124	mV
t _{LOW}	EN signal low time during cycling	RTIMER = GND, IL = 1 A, I _{VOUT} = 2 A	See 图 7-1	9, 10, 11		20		μs
V _{INEN}	VIN percentage for enable ⁽²⁾			4, 5, 6		75%		
I _{EN}	EN pin input leakage current	EN = VIN = 5 V		1, 2, 3			12	nA

6.5 Electrical Characteristics: All Devices (续)

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	SUBGROUP (1)	MIN	TYP	MAX	UNIT
OVERVOLTAGE PROTECTION (OVP)							
V _{OVPR}	OVPR threshold voltage, rising		1, 2, 3	0.52	0.57	0.63	V
V _{OVPF}	OVPF threshold voltage, falling		1, 2, 3	0.5	0.55	0.59	V
HYST _{OVP}	OVP hysteresis voltage	1.6 V < VIN < 7 V	1, 2, 3		20	55	mV
I _{OVP}	OVP pin input leakage current		1, 2, 3			15	nA
CURRENT LIMIT AND CURRENT SENSE							
t _{CSEN}	Time for valid CS output after enable	C _{SS} = 120 nF	9, 10, 11			5	ms
Minimum VOUT current for valid CS output			1, 2, 3	750			mA
VOUT current change to CS change delay time		0.5-A rising step, 100 mA/μs, 1.5 V ≤ VIN ≤ 7 V	9, 10, 11		16	74	μs
VOUT current change to CS change delay time		0.5-A falling step, 100 mA/μs, 1.5 V ≤ VIN ≤ 7 V	9, 10, 11		16	73	μs
CS pin accuracy		0.75 A ≤ I _{VOUT} ≤ 7.5 A	4, 5, 6	- 10%		10%	
CS pin voltage		0.75 A ≤ I _{VOUT} ≤ 7.5 A, no OCP	1, 2, 3			VIN - 0.4	V
Current limit setting, I _{IL}	I _{VOUT} ≤ 1 A		1, 2, 3	I _{VOUT} + 0.5		A	
	1A < I _{VOUT} ≤ 3 A		1, 2, 3	I _{VOUT} + 1			
	I _{VOUT} > 3 A		1, 2, 3	I _{VOUT} + 1.5			
Programmable current limit accuracy		1.5 V ≤ VIN ≤ 7 V	4, 5, 6	- 20%		20%	
Fast trip off current limit		VIN = 5 V, 10-mΩ short in 10 μs			22		A
TIMERS							
I _{LTIMER}	LTIMER charge current		1, 2, 3	0.7	1	1.38	μA
PD _{LTIMER}	LTIMER internal pull-down resistance	40 mV on LTIMER pin	1, 2, 3		38	153	Ω
I _{RTIMER}	RTIMER charge current		1, 2, 3	0.7	1	1.38	μA
PD _{RTIMER}	RTIMER internal pull-down resistance	40 mV on RTIMER pin	1, 2, 3		38	153	Ω
THERMAL SHUTDOWN							
Thermal shutdown		VIN = 5 V			175		°C
Thermal shutdown hysteresis		VIN = 5 V			20		°C

(1) For subgroup definitions, see [Quality Conformance Inspection](#) table.

(2) V_{IN} must be $\geq 75\%$ of its final value before EN is asserted only if $V_{IN_{SR}} > V_{OUT_{SR}}$.

6.6 Electrical Characteristics: CFP and KGD Options

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	SUBGROUP ⁽¹⁾	MIN	TYP	MAX	UNIT	
POWER SUPPLIES AND CURRENTS								
I _{RCP}	Reverse current protection leakage current	EN = 0 V, VIN = 0 to 7 V, VOUT = 0 to 7 V for VOUT > VIN	1, 2, 3	0.45	2.5	mA		
		EN = 7 V, VIN = 0 V, VOUT = 0 to 7 V						
CURRENT LIMIT AND CURRENT SENSE								
Fast trip off off-time ⁽²⁾		VIN = 5 V, C _{SS} = 2.7 nF	9, 10, 11	61	158	μs		
Internal current limit timer (fast trip off current limit) ⁽²⁾		VIN = 5 V, I _{VOUT} = 3 A, IL = 6 A, ILTIMER = VIN, 10-mΩ short in 10 μs	9, 10, 11	15	35			
RESISTANCE CHARACTERISTICS								
R _{ON}	ON-state resistance, lead length = 2.5 mm	VIN = 7 V, I _{IL} = 7.5 A	1, 2, 3	- 55°C		24	mΩ	
				- 40°C		26		
				25°C		31		34
				85°C		37		40
				125°C		41		45
		VIN = 5 V, I _{IL} = 7.5 A	1, 2, 3	- 55°C		26		
				- 40°C		27		
				25°C		32		35
				85°C		39		42
				125°C		43		47
		VIN = 3.3 V, I _{IL} = 7.5 A	1, 2, 3	- 55°C		28		
				- 40°C		30		
				25°C		35		38
				85°C		42		46
				125°C		47		52
		VIN = 1.8 V, I _{IL} = 7.5 A	1, 2, 3	- 55°C		36		
				- 40°C		39		
				25°C		45		51
				85°C		55		62
				125°C		61		70
		VIN = 1.5 V, I _{IL} = 7.5 A	1, 2, 3	- 55°C		44		
				- 40°C		48		
				25°C		52		63
				85°C		63		77
				125°C		70		87

(1) For subgroup definitions, see [Quality Conformance Inspection](#) table.

(2) Bench verified; not tested in production

6.7 Electrical Characteristics: HTSSOP Option

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS		SUBGROUP ⁽¹⁾	MIN	TYP	MAX	UNIT
POWER SUPPLIES AND CURRENTS								
I _{RCP}	Reverse current protection leakage current	EN = 0 V, VIN = 0 to 7 V, VOUT = 0 to 7 V for VOUT > VIN	SEP	1, 2, 3	0.45	2.5	mA	
			QMLP pre TID					
			QMLP, after TID = 100 krad		0.45	20		
		EN = 7 V, VIN = 0 V, VOUT = 0 to 7 V	SEP		0.45	2.5		
			QMLP pre TID					
			QMLP, after TID = 100 krad		0.45	20		
CURRENT LIMIT AND CURRENT SENSE								
Fast trip off off-time		VIN = 5 V, C _{SS} = 2.7 nF		9, 10, 11	61		μs	
Internal current limit timer (fast trip off current limit)		VIN = 5 V, I _{VOUT} = 3 A, IL = 6 A, ILTIMER = VIN, 10-mΩ short in 10 μs		9, 10, 11	15			
RESISTANCE CHARACTERISTICS								
R _{ON}	ON-state resistance	VIN = 7 V, I _{IL} = 7.5 A	- 55°C	1, 2, 3	15.9	17	mΩ	
			- 40°C		16.9			
			25°C		19.9	21		
			85°C		22.9			
			125°C		25	27		
		VIN = 5 V, I _{IL} = 7.5 A	- 55°C	1, 2, 3	17	18		
			- 40°C		18			
			25°C		21.4	23		
			85°C		24.8			
			125°C		27	29		
		VIN = 3.3 V, I _{IL} = 7.5 A	- 55°C	1, 2, 3	19.2	21		
			- 40°C		20.4			
			25°C		24.5	26		
			85°C		28.5			
			125°C		31.2	33		
		VIN = 1.8 V, I _{IL} = 7.5 A	- 55°C	1, 2, 3	27.1	29		
			- 40°C		28.7			
			25°C		34.9	37		
			85°C		41			
			125°C		44.9	48		
		VIN = 1.5 V, I _{IL} = 7.5 A	- 55°C	1, 2, 3	33	36		
			- 40°C		35			
			25°C		42.7	46		
			85°C		46.2			
			125°C		55	59		

(1) For subgroup definitions, see [Quality Conformance Inspection](#) table.

6.8 Switching Characteristics (All Devices)

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
VIN = EN = 5 V, TA = 25°C (unless otherwise noted)						
t _{ON}	Turn-on time	R _L = 10 Ω, C _L = 10 μF, C _{SS} = 1000 pF		208		μs
t _{OFF}	Turn-off time	R _L = 10 Ω, C _L = 10 μF, C _{SS} = 1000 pF		60		μs
t _F	VO _{UT} fall time	R _L = 10 Ω, C _L = 10 μF, C _{SS} = 1000 pF		90		μs
t _{ASSERT}	OVP assert time	R _L = 10 Ω, C _L = 10 μF, C _{SS} = 1000 pF		4.5		μs
t _{DEASSERT}	OVP deassert time	R _L = 10 Ω, C _L = 10 μF, C _{SS} = 1000 pF		9.6		μs
VIN = EN = 1.5 V, TA = 25°C (unless otherwise noted)						
t _{ON}	Turn-on time	R _L = 10 Ω, C _L = 10 μF, C _{SS} = 1000 pF		173		μs
t _{OFF}	Turn-off time	R _L = 10 Ω, C _L = 10 μF, C _{SS} = 1000 pF		64		μs
t _F	VO _{UT} fall time	R _L = 10 Ω, C _L = 10 μF, C _{SS} = 1000 pF		70		μs
t _{ASSERT}	OVP assert time	R _L = 10 Ω, C _L = 10 μF, C _{SS} = 1000 pF		2.65		μs
t _{DEASSERT}	OVP deassert time	R _L = 10 Ω, C _L = 10 μF, C _{SS} = 1000 pF		6.56		μs

6.9 Quality Conformance Inspection

MIL-STD-883, Method 5005 - Group A

SUBGROUP	DESCRIPTION	TEMP (°C)
1	Static tests at	25
2	Static tests at	125
3	Static tests at	– 55
4	Dynamic tests at	25
5	Dynamic tests at	125
6	Dynamic tests at	– 55
7	Functional tests at	25
8A	Functional tests at	125
8B	Functional tests at	– 55
9	Switching tests at	25
10	Switching tests at	125
11	Switching tests at	– 55

6.10 Typical Characteristics

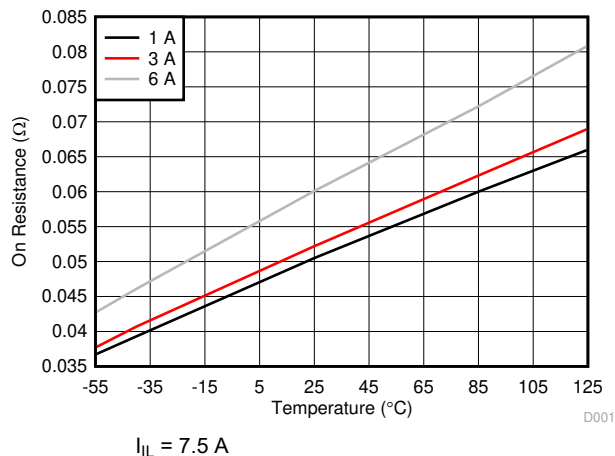


图 6-1. On-Resistance vs Temperature Across Loads for CFP and KGD at $V_{IN} = 1.5 \text{ V}$

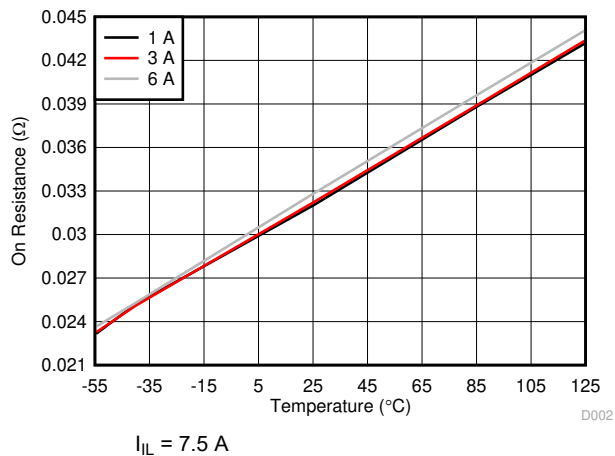


图 6-2. On-Resistance vs Temperature Across Loads for CFP and KGD at $V_{IN} = 5 \text{ V}$

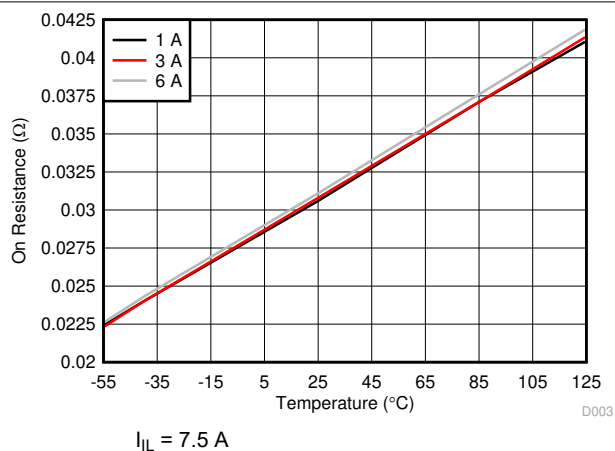


图 6-3. On-Resistance vs Temperature Across Loads for CFP and KGD at $V_{IN} = 7 \text{ V}$

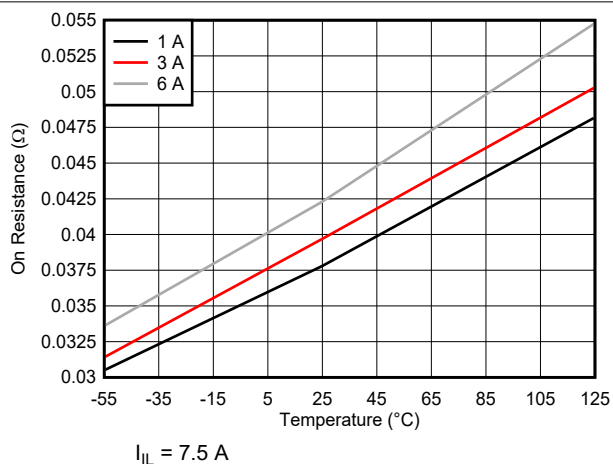


图 6-4. On-Resistance vs Temperature Across Loads for HTSSOP at $V_{IN} = 1.5 \text{ V}$

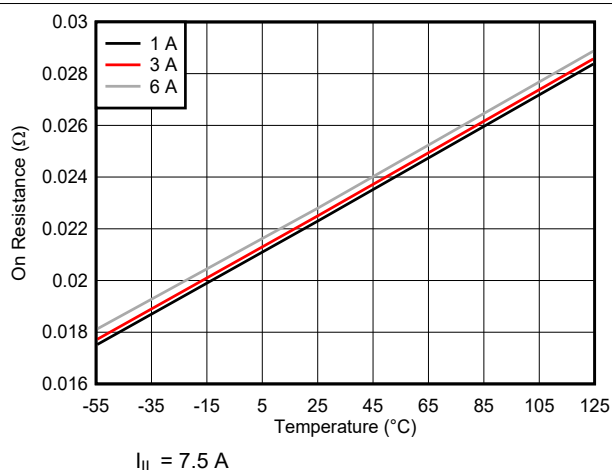


图 6-5. On-Resistance vs Temperature Across Loads for HTSSOP at $V_{IN} = 5 \text{ V}$

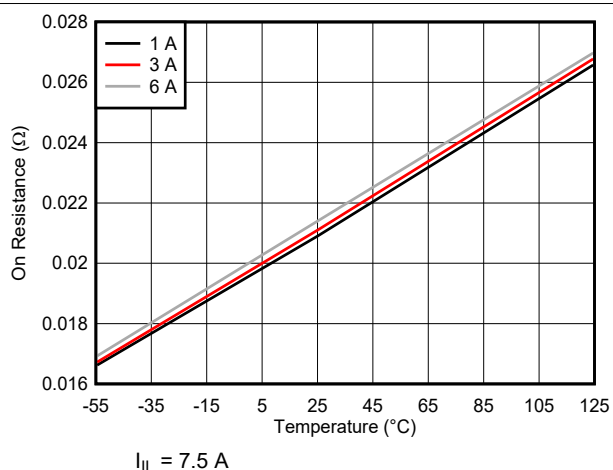


图 6-6. On-Resistance vs Temperature Across Loads for HTSSOP at $V_{IN} = 7 \text{ V}$

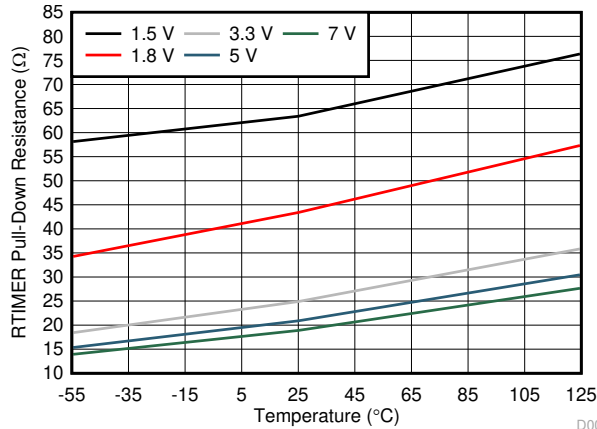


图 6-7. RTIMER Pull-Down Resistance vs Temperature Across VIN

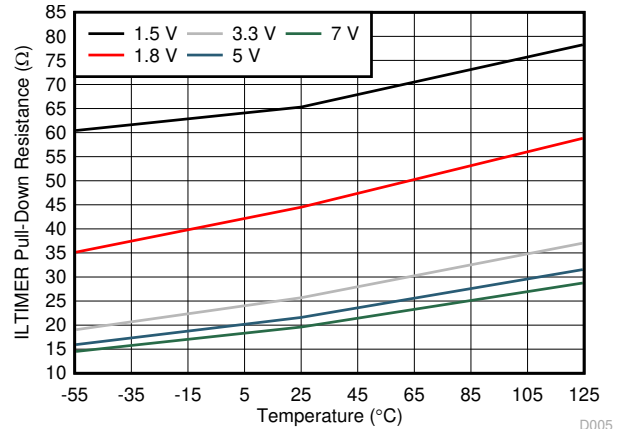


图 6-8. ILTIMER Pull-Down Resistance vs Temperature Across VIN

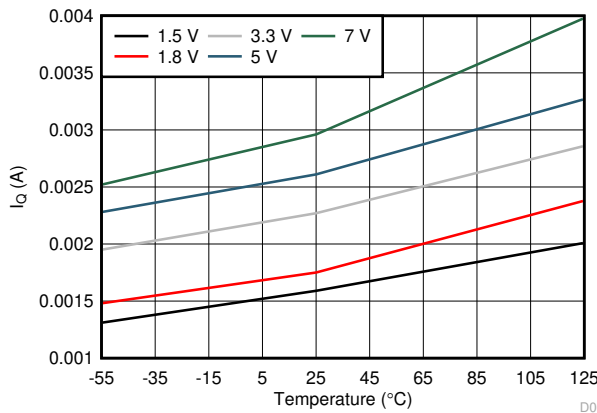


图 6-9. I_Q vs Temperature Across VIN

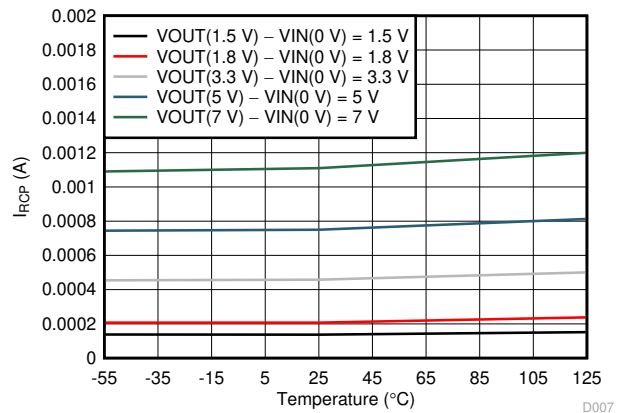


图 6-10. I_{RCP} vs Temperature With EN = 7 V

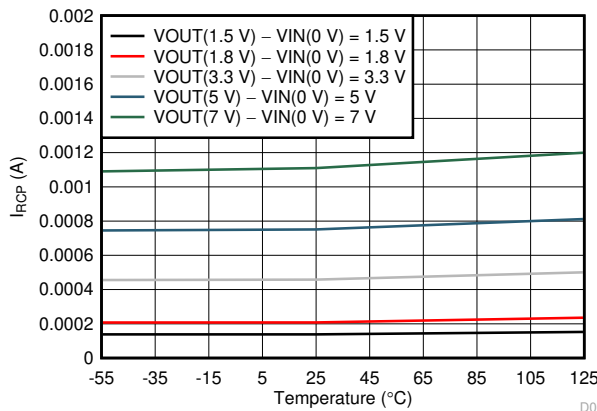


图 6-11. I_{RCP} vs Temperature With EN = GND

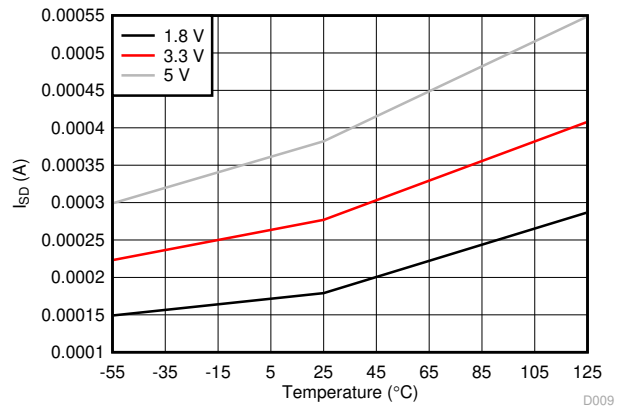


图 6-12. I_{SD} VIN vs Temperature Across VIN

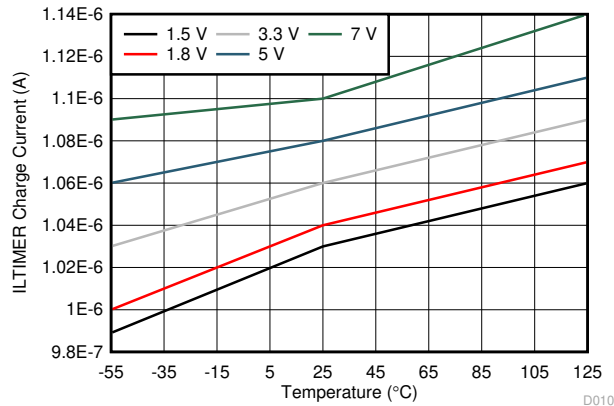


图 6-13. ILTIMER Charge Current vs Temperature Across VIN

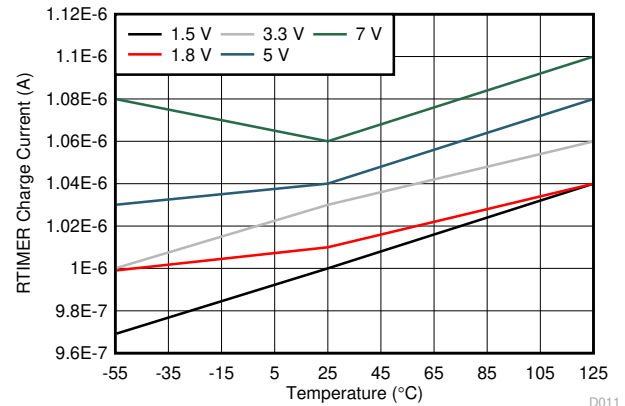


图 6-14. RTIMER Charge Current vs Temperature Across VIN

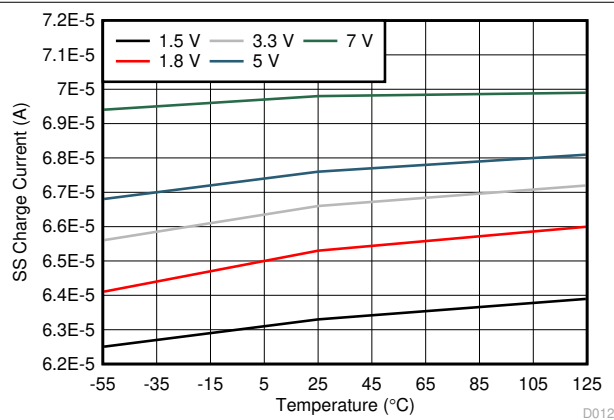
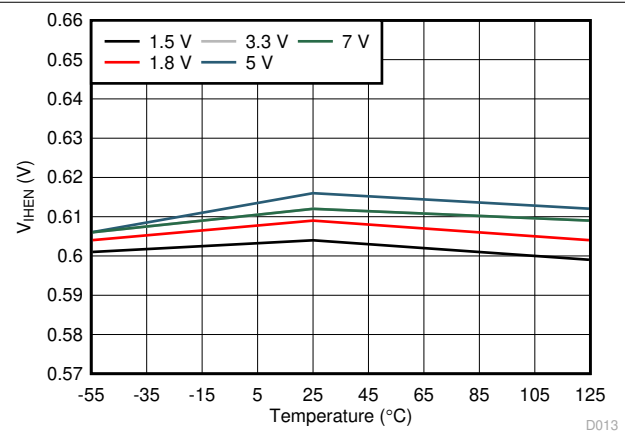
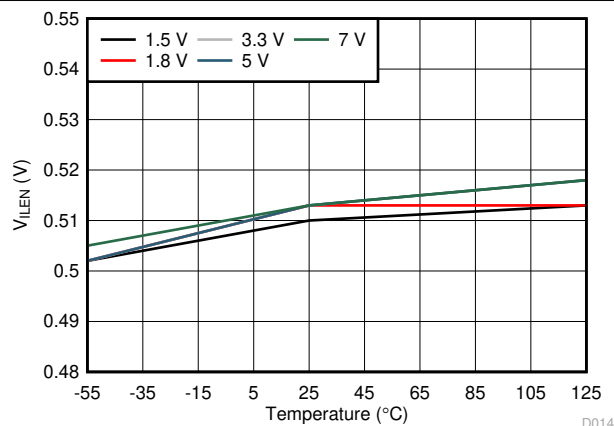


图 6-15. SS Charge Current vs Temperature Across VIN



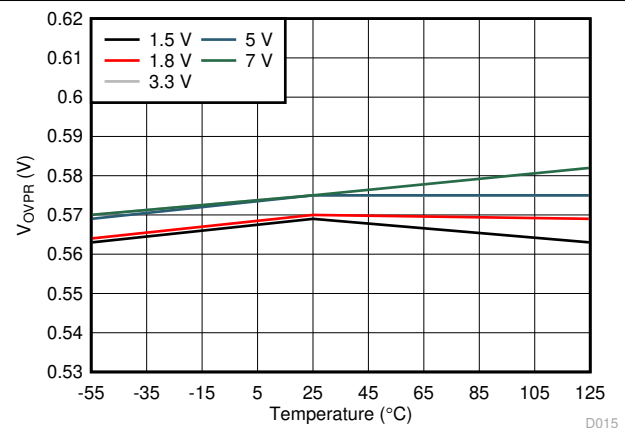
EN pin driven directly

图 6-16. V_{IHEN} vs Temperature Across VIN



EN pin driven directly

图 6-17. V_{ILEN} vs Temperature Across VIN



OVP pin driven directly

Waveform at 3.3 V is obscured by the 5 V

图 6-18. V_{OVPR} vs Temperature Across VIN

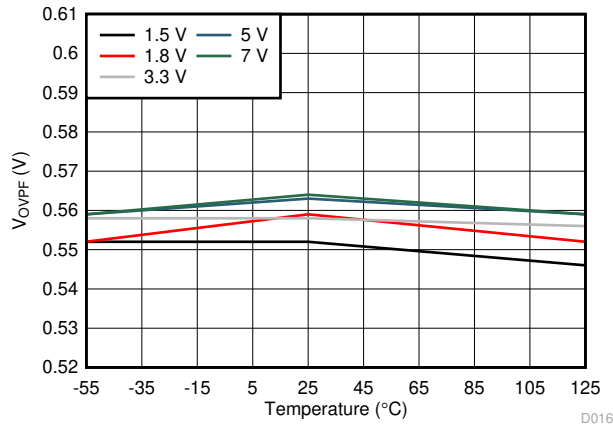


图 6-19. V_{OVPF} vs Temperature Across VIN

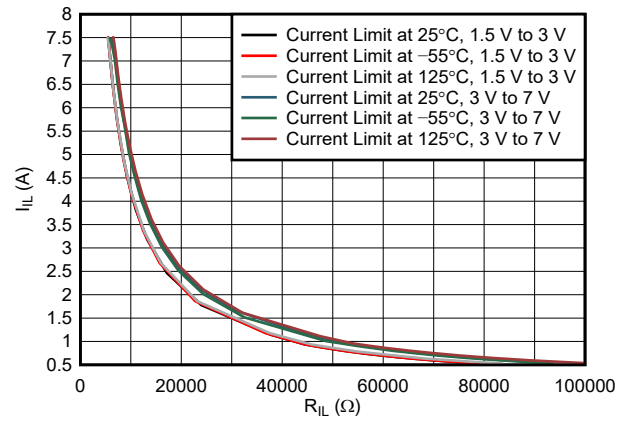


图 6-20. I_{IL} vs R_{IL} Across Temperature

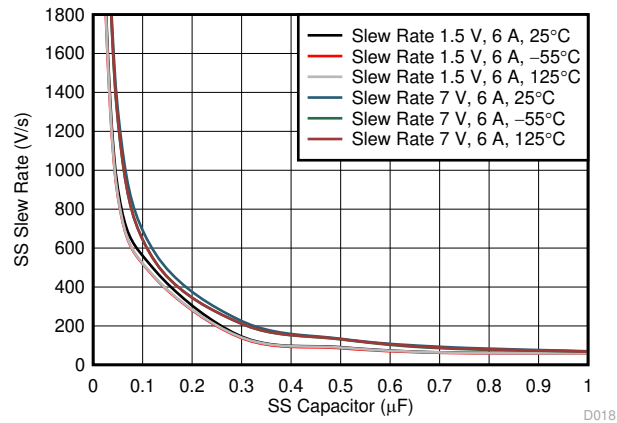


图 6-21. SS Slew Rate vs SS Capacitor Across Temperature

7 Parameter Measurement Information

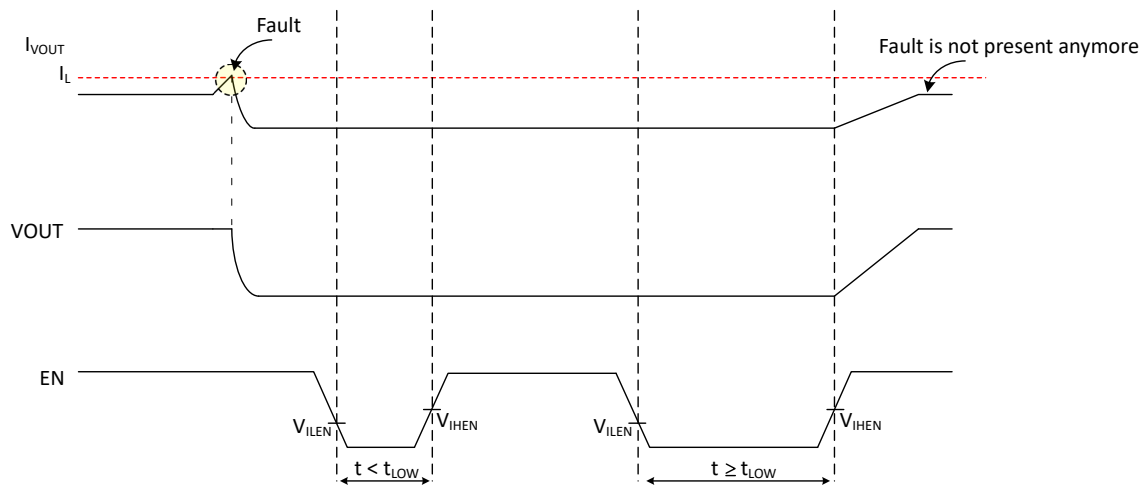


图 7-1. EN Signal Low Time to Restart Device (t_{LOW})

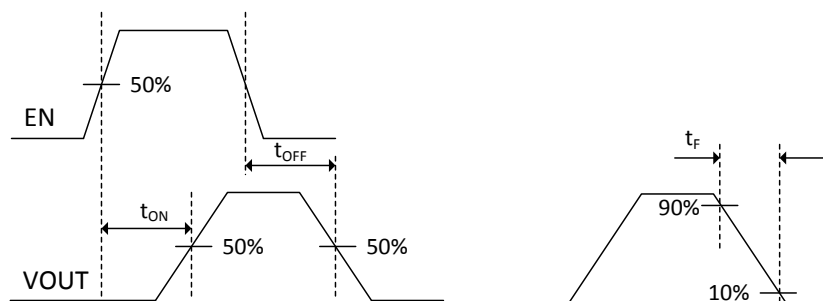


图 7-2. Turn-On (t_{ON}), Turn-Off (t_{OFF}) and V_{OUT} Fall Time (t_F) Waveforms

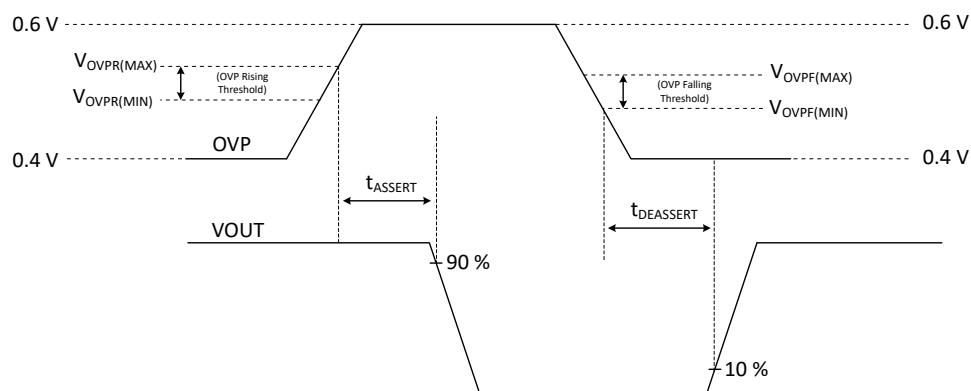


图 7-3. OVP Assert (t_{ASSERT}) and OVP Deassert ($t_{DEASSERT}$) Waveforms

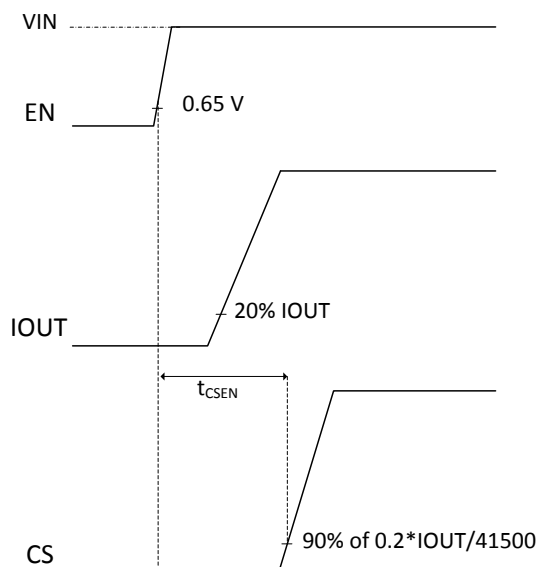


图 7-4. t_{CSEN} Waveforms

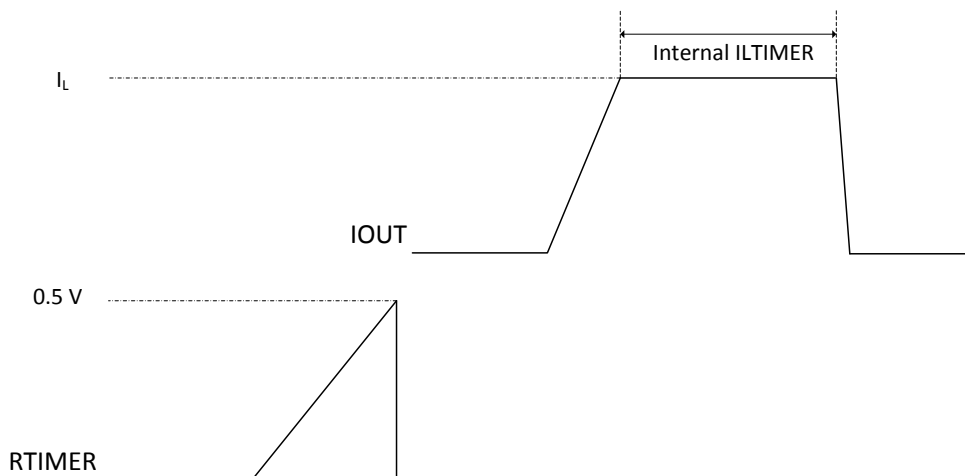


图 7-5. Internal ILTIMER Waveforms

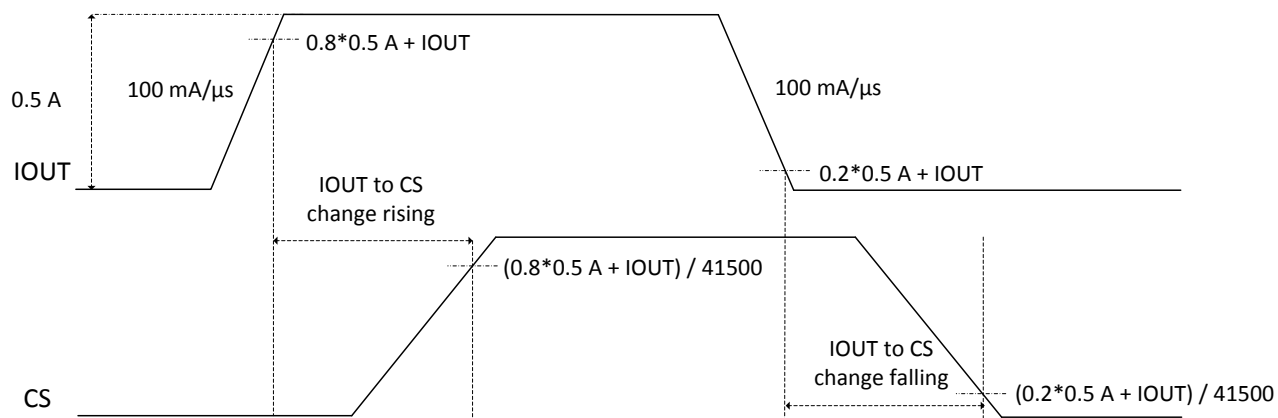


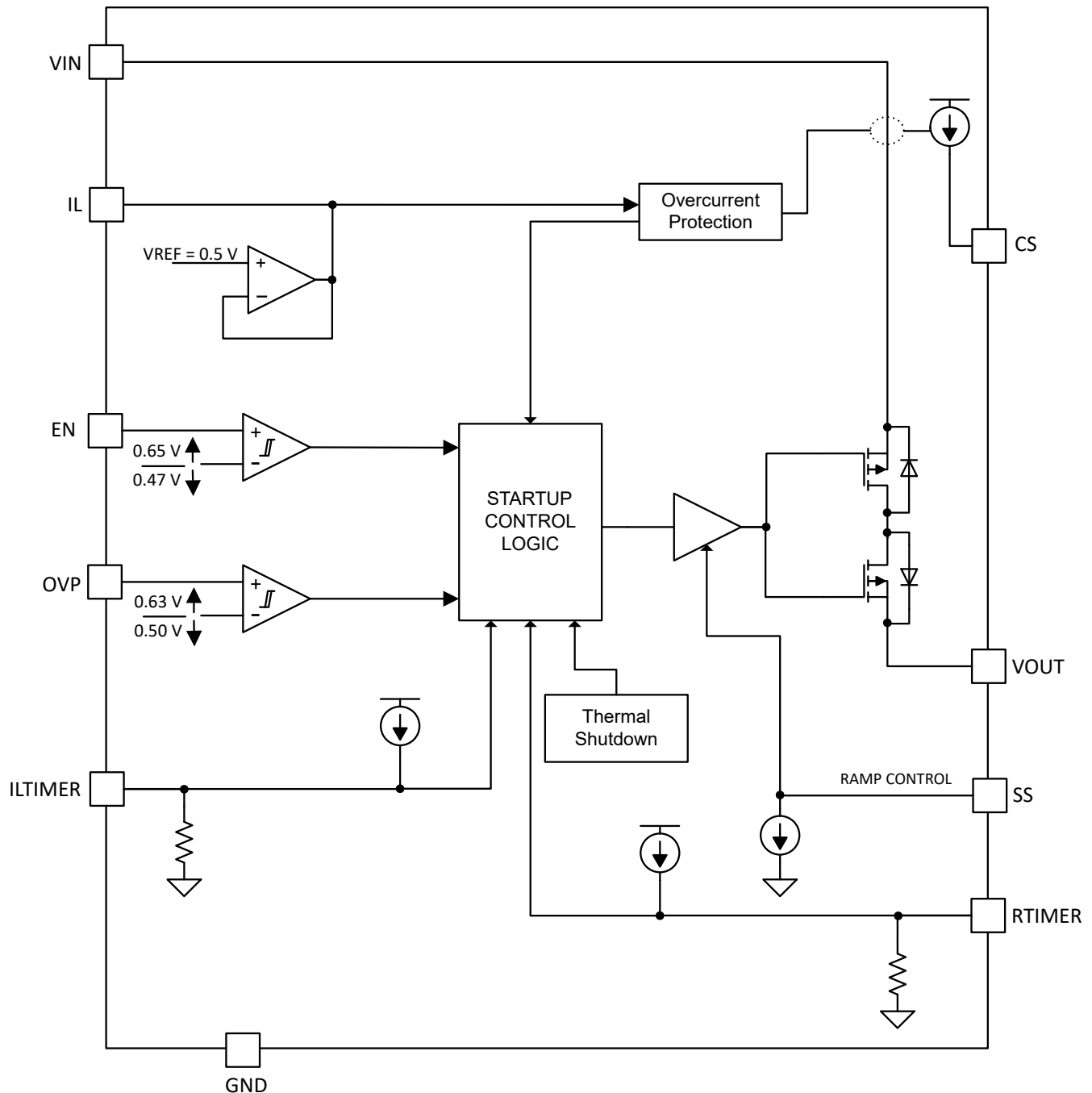
图 7-6. VOUT Current to CS Change Delay Time

8 Detailed Description

8.1 Overview

The TPS7H2201 device is a single channel, 6-A eFuse with a programmable slew rate for applications that require specific rise-time as well as programmable current limit for protection purposes. In addition, the TPS7H2201 features a reverse current protection capability for power distribution applications.

8.2 Functional Block Diagram



8.3 Feature Description

8.3.1 Enable, Undervoltage, and Overvoltage Protection

图 8-1 shows how resistor dividers from VIN connected to the EN and OVP pins can be used to set the UVLO and OVP trip voltages. The EN pin controls the ON and OFF state of the internal FET. A voltage at this pin greater than V_{IHEN} turns on the FET and a voltage less than V_{ILEN} turns it off. The addition of an external resistor divider from VIN allows the EN pin to configure a different enable rising voltage or an undervoltage monitor (UVLO) based on the V_{IHEN} and V_{ILEN} specifications respectively. Typically, applications are optimized to either configure the enable rising voltage or the UVLO threshold. As an example, 方程式 1 can be used to calculate the UVLO trip point fixing $R_{TOP_EN} = 100\text{ k}\Omega$.

In a similar way to the EN pin, the overvoltage protection (OVP) feature of the device can be configured using a resistor divider from VIN connected to the OVP pin. The trip voltage for the OVP has to be less than the absolute maximum VIN voltage. A voltage at the OVP pin greater than V_{OVPR} will trip the OVP feature and will turn off the FET and a voltage less than V_{OVPF} will keep the FET on. If this feature is not desired, the OVP pin should be grounded. 方程式 2 can be used to calculate the rising OVP trip point fixing $R_{TOP_OVP} = 100\text{ k}\Omega$.

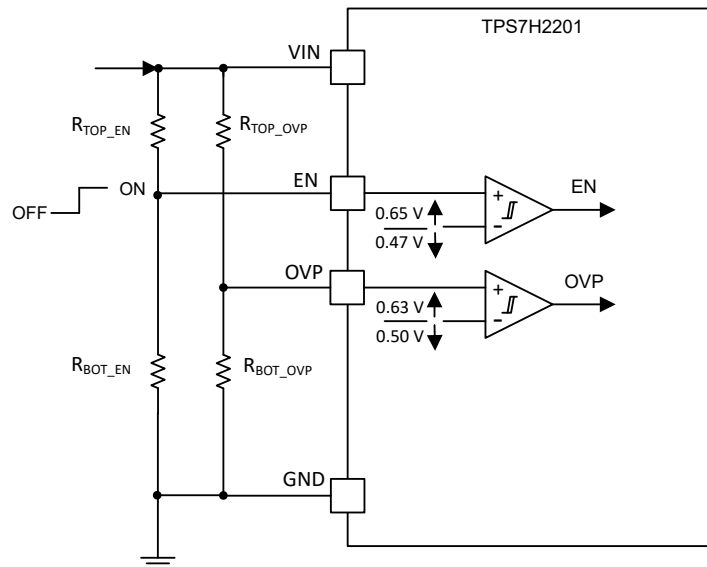


图 8-1. UVLO and OVP Thresholds Set by Resistor Dividers

$$R_{BOT_EN} (k\Omega) \leq \frac{47}{V_{UVLO_TRIP} (V) - 0.47} \quad (1)$$

$$R_{BOT_OVP} (k\Omega) \geq \frac{63}{V_{OVP_TRIP} (V) - 0.63} \quad (2)$$

8.3.2 Adjustable Rise Time

An external capacitor, C_{SS} , connected between the VOUT and SS pins sets the slew rate. The desired slew rate $VOUT_{SR}$ is determined by t_r , the rise time in seconds, and ΔV , the change in VOUT voltage in Volts as shown in 方程式 3.

$$VOUT_{SR} (V/s) = \frac{\Delta V_{OUT} (V)}{t_r (s)} \quad (3)$$

In order to avoid false trips due to the programmable current limit, the desired slew rate must be less than $V_{OUTSR,MAX}$ as shown in 方程式 4, where I_L is the programmed current limit, I_{VOUT} is the normal operation current flowing through the switch, and C_{OUT} is the output capacitor.

$$V_{OUTSR,MAX} (V/s) < \frac{0.8 \times I_L (A) - 0.95 \times I_{VOUT} (A)}{C_{OUT} (F)} \quad (4)$$

Once the slew rate has been calculated and meeting the constraint in 方程式 4, the C_{SS} capacitor is then calculated using 方程式 5 for $V_{IN} < 3V$ and $I_{OUT} \geq 3A$ applications. For all other applications, use 方程式 6.

$$C_{SS} (\mu F) = \frac{45}{V_{OUTSR} (V/s)} \quad (5)$$

for $V_{IN} < 3V$ and $I_{OUT} \geq 3A$

$$C_{SS} (\mu F) = \frac{65}{V_{OUTSR} (V/s)} \quad (6)$$

for all other conditions

8.3.3 Programmable Current Limiting

A current limit can be programmed using an external resistor connected from the IL pin to GND. This programmed current limit ($\pm 20\%$ accurate) refers to the continuous current through the device and therefore, when operated at its maximum current rating (6 A), the programmed current limit needs to be set 20% higher. As shown in 图 8-2, a current limit event of this nature is defined as a soft short. The resistor value R_{IL} , can be calculated using 方程式 7 for $V_{IN} \leq 3V$, and 方程式 8 for $V_{IN} > 3V$, where I_L is the programmed current limit value in amperes. This programmable current limiting feature is different from the internal current limiting activated during fast trip mode as shown in 图 8-3. A current limit event in this case is defined as a hard short and this current limit (typical of 22 A) cannot be programmed.

$$R_{IL} (\Omega) = \frac{45500}{I_L (A)} \quad (7)$$

for $V_{IN} \leq 3V$

$$R_{IL} (\Omega) = \frac{49000}{I_L (A)} \quad (8)$$

for $V_{IN} > 3V$

8.3.4 Programmable Fault Timer

A capacitor connected from the ILTIMER pin to GND determines the programmable current limit fault time duration. The ILTIMER pin will charge the capacitor to 0.5 V during an overload condition and will discharge it otherwise through an internal pull down resistance. The time that the device will be in current limit before turning off is configured by $C_{ILTIMER}$ and the time can be calculated using 方程式 9. Connecting this pin to V_{IN} will cause the device to be disabled once the internal current limit timer expires as shown in 图 7-5. However, connecting it to GND will disable the internal timer functionality completely and therefore, in the case of a short, the device will remain at the programmed current limit indefinitely. When using the internal timer, the programmable current limit may not have time to settle to its programmed value. Because of this, the programmable current limit could briefly fall outside of its defined accuracy threshold. The fast trip off current limit, however, will remain valid.

$$t(\mu s) = \frac{C(pF)}{2} \quad (9)$$

The time that the device remains disabled after the current limit timer expires is configurable through a capacitor connected from the RTIMER pin to GND. The RTIMER pin will charge the capacitor to 0.5 V after the switch is turned off and will discharge it otherwise. The time can be calculated using [方程式 9](#). Connecting this pin to GND will keep the device disabled and it will require the device to be enabled by cycling the EN pin (Refer to [EN Signal Low Time to Restart Device \(t_{LOW}\)](#)). The behavior of the ILTIMER and RTIMER pins for a soft short, hard short and internal timer conditions are shown in [图 8-2](#), [图 8-3](#), and [图 8-4](#), respectively. Please notice that [图 8-2](#) and [图 8-3](#) assume the fault is not present after the switch has been disabled and enabled again (retry mode). If the fault is present after the retry mode, the device will go into current limit mode and this cycle will repeat until the fault is no longer present.

[表 8-1](#) 和 [表 8-2](#) summarizes the fault duration time and retry time based on the pin conditions.

表 8-1. Fault Time Duration for ILTIMER Pin Conditions

ILTIMER Pin Condition	Fault Time Duration During Overload
VIN	15 μs (typ), 35 μs (max)
GND	Indefinitely
Capacitor to GND (C _{ILTIMER})	方程式 9
Float	Not valid (do not float pin)

表 8-2. Time to Retry During an Overload Condition for RTIMER Pin Conditions

RTIMER Pin Condition	Time to Retry During an Overload
GND	Disabled (switch off) until EN is low for t > t _{LOW} (20 μs)
Capacitor to GND (C _{RTIMER})	方程式 9
Float	Not valid (do not float pin)

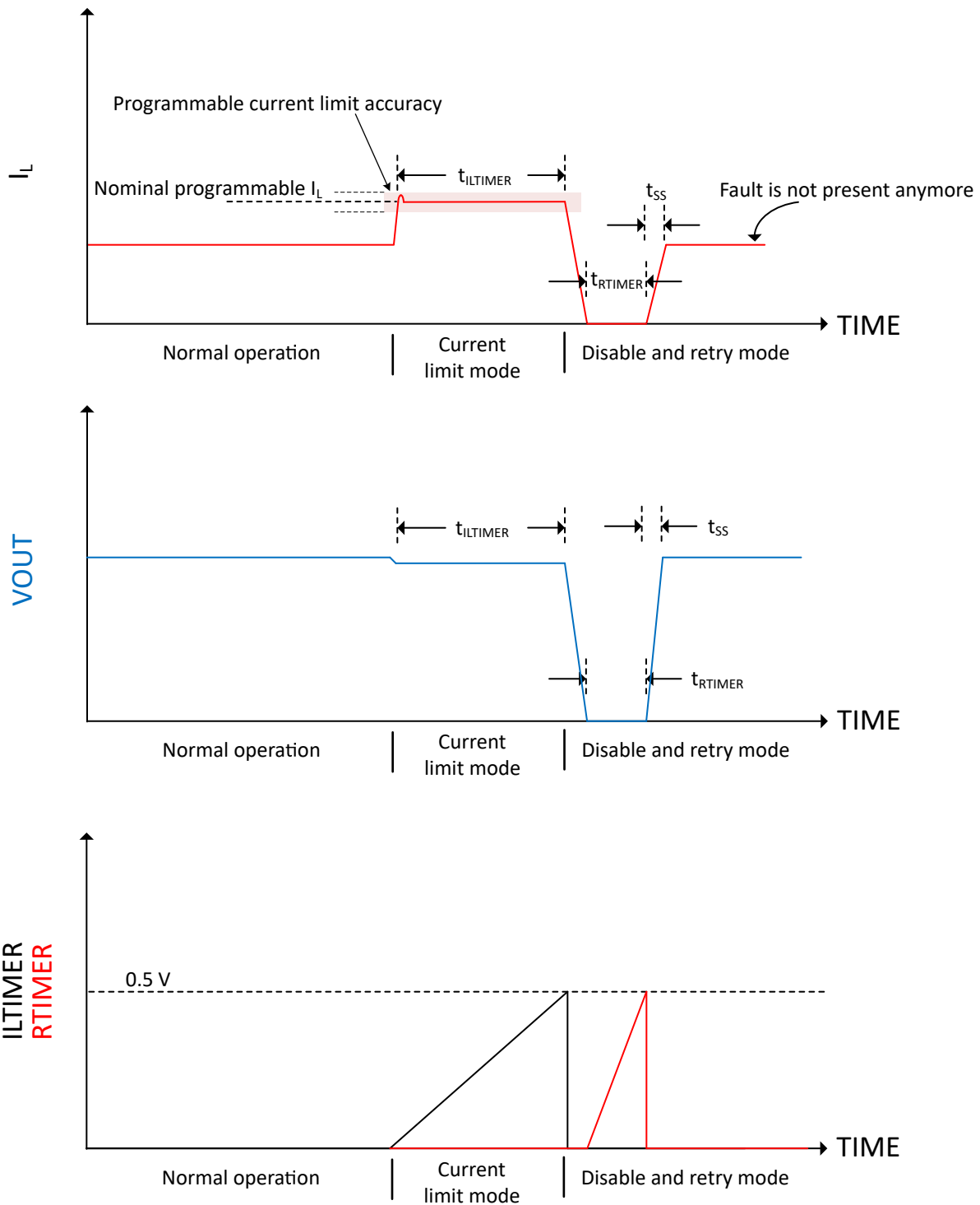


图 8-2. Soft Short Programmable Fault Timer Operation Connecting Capacitors to ILTIMER and RTIMER Pins

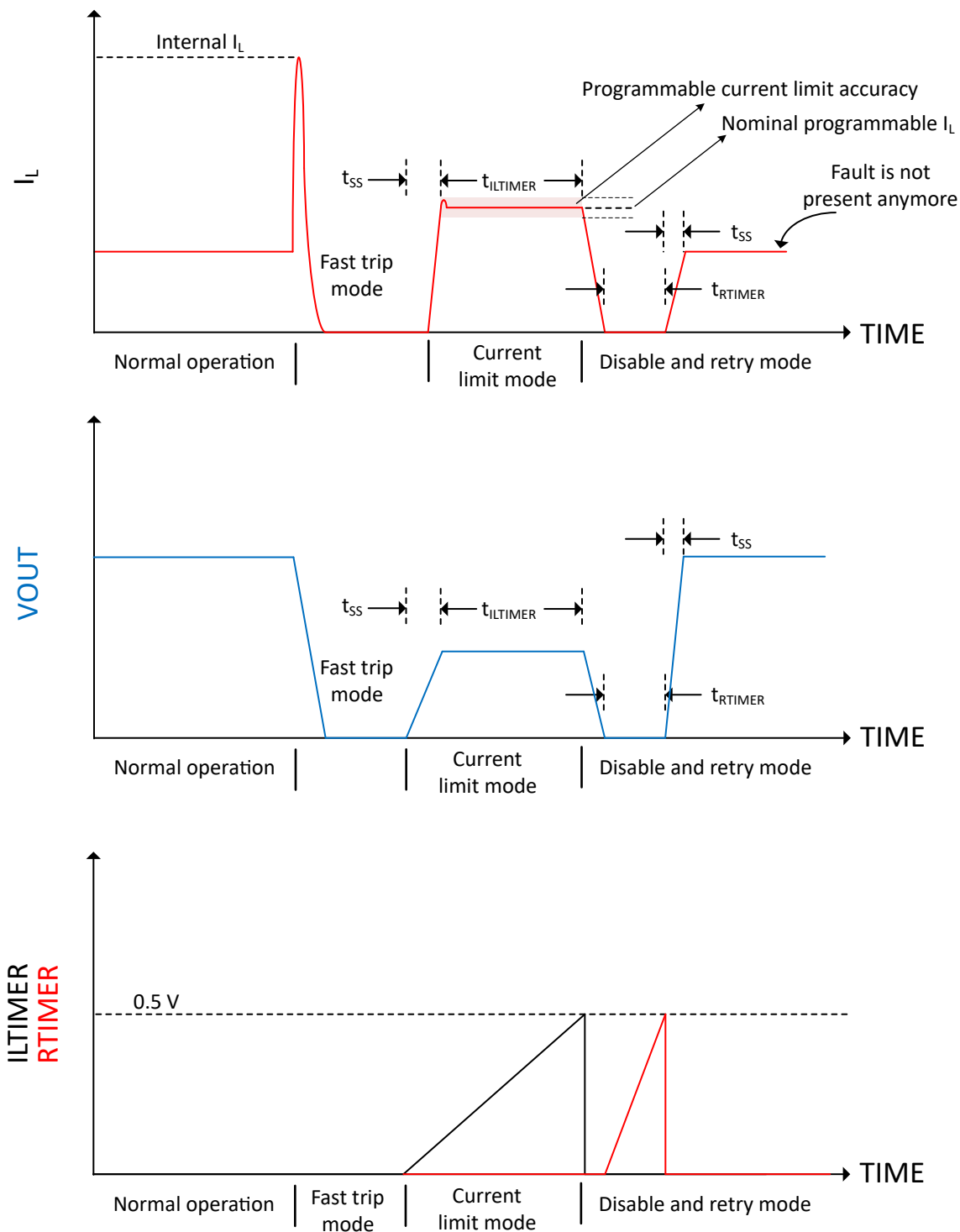


图 8-3. Hard Short Programmable Fault Timer Operation Connecting Capacitors to ILTIMER and RTIMER Pins

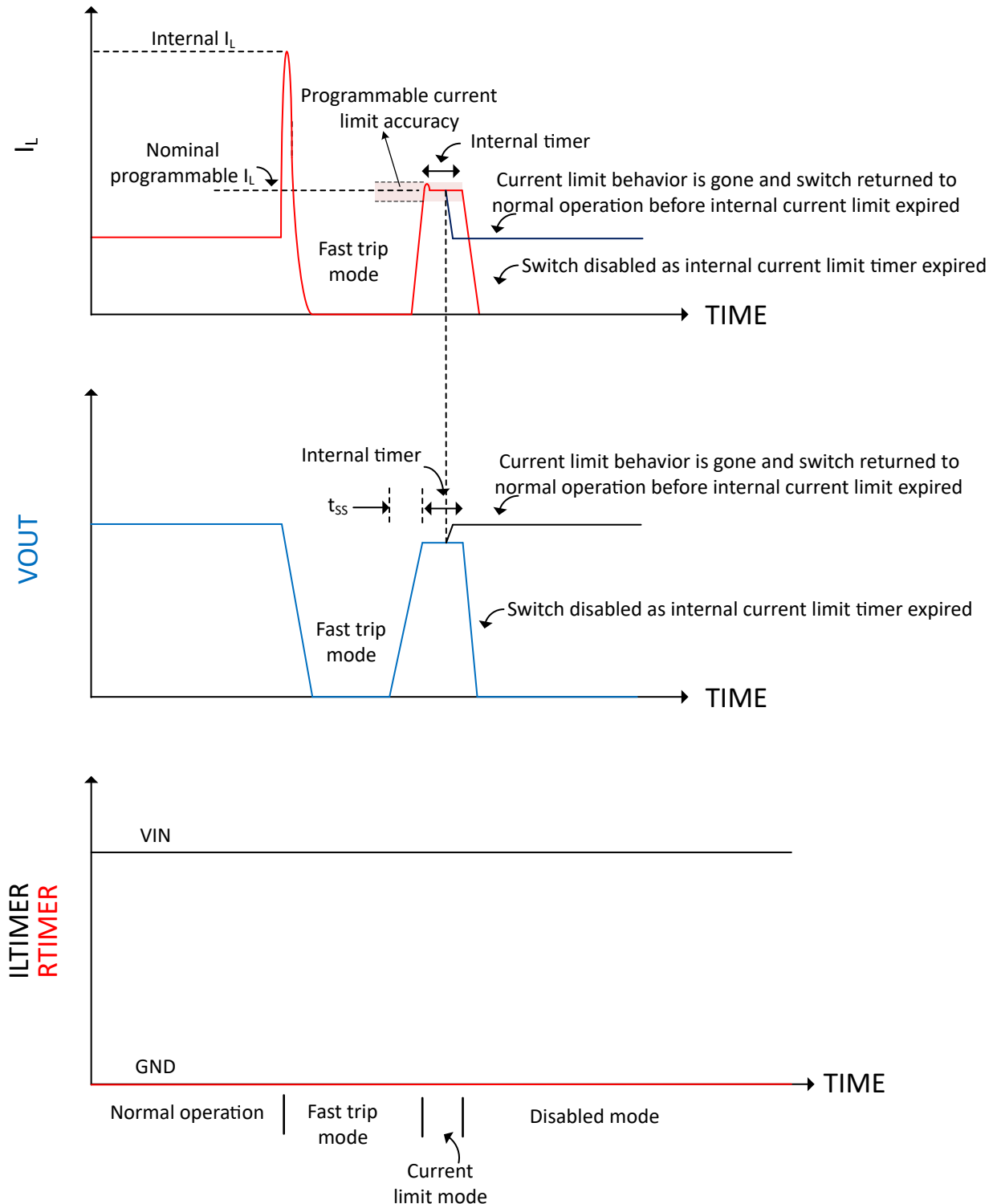


图 8-4. Programmable Fault Timer Operation Using the Internal Current Limit Timer and Disabling the Retry Mode

The programmable fault timers, ILTIMER and RTIMER, should be set in such a way that the capacitor for one timer is discharged before the other timer expires to ensure proper operation. In the specific case of using the internal ILTIMER, the RTIMER capacitor should be sized such that it is discharged before the internal ILTIMER

expires, assuming the fault is still present. 图 8-5 shows a situation where this constraint is not met as the RTIMER is much larger than the ILTIMER and therefore, the CRTIMER is not discharged before the CILTIMER reaches 0.5 V, which is when the ILTIMER will expire. In order to avoid this situation, the constraint shown in 方程式 10 must be met. Using this equation, once a capacitor for a timer has been selected (C₁ in 方程式 10), the maximum value for the capacitor of the second timer can be determined. The internal pull-down resistance for each of the timers can be found in the *Electrical Characteristics: All Devices* table. For the situation shown in 图 8-5, C₁ and R_{PD1} in 方程式 10 correspond to the RTIMER.

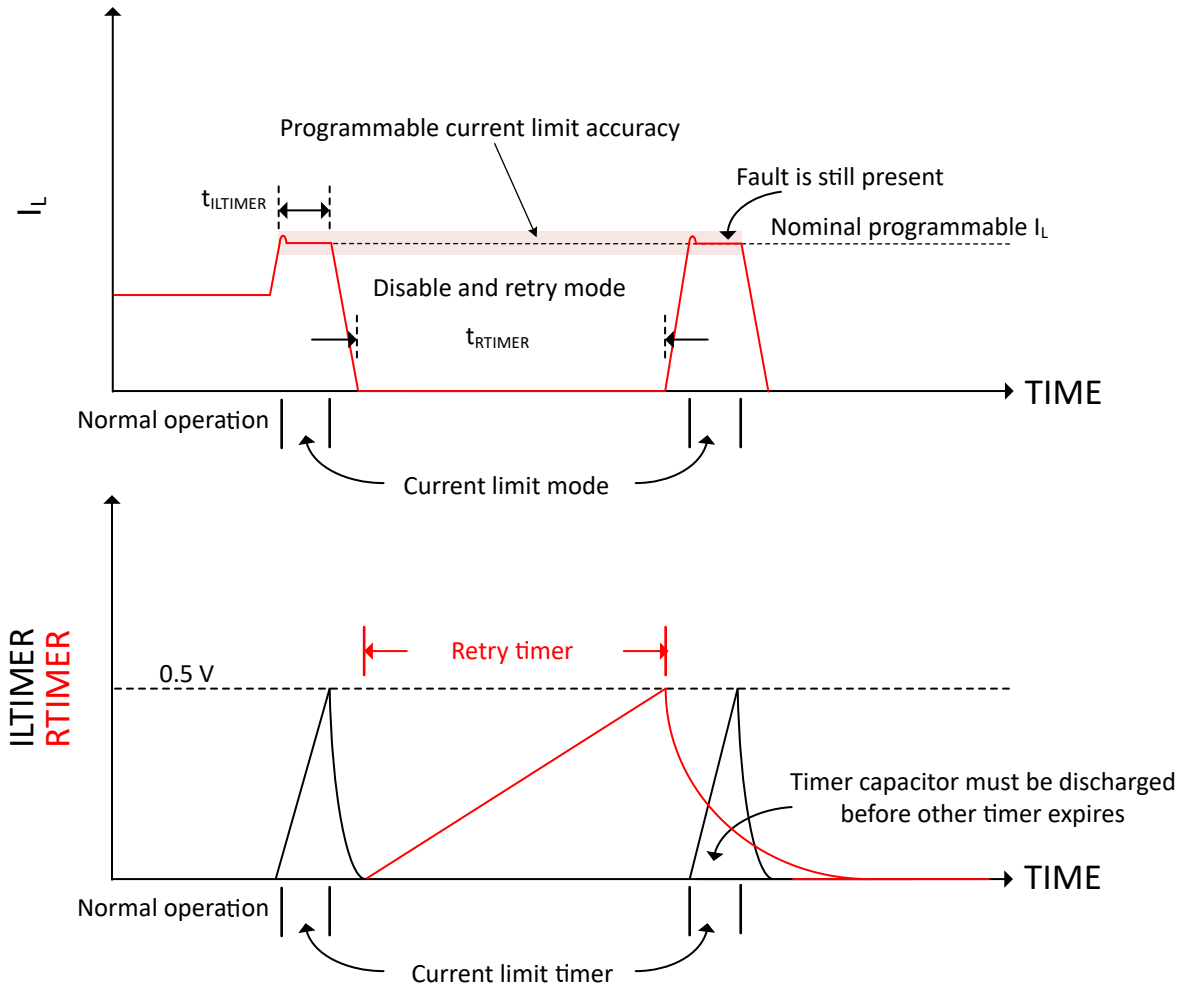


图 8-5. Programmable Fault Timer Capacitors Constraint

$$C_1(\mu\text{F}) < \frac{C_2(\text{pF})}{8 \times R_{PD1}(\Omega)} \quad (10)$$

8.3.5 Current Sense

This pin will output a current proportional to the output current of the switch for current sensing applications. A resistor to GND will convert this current to voltage for current sensing purposes. The output current will be the switch current divided by 41,500. The CS pin will have a valid output 5 ms after the device has been enabled. To operate the current sense in the linear region, the voltage at the CS pin at the application maximum load, should not exceed the CS pin voltage specification (V_{IN} - 400 mV).

8.3.6 Parallel Operation

The TPS7H2201 can be configured in parallel operation either to increase the current capability, up to 12 A, or to reduce the on-state resistance. In this case, all pins are shared as shown in [图 8-6](#), except the current limit resistor (R_{IL}) for proper operation of the internal current limit loop. The current limiting resistors must be sized as described in the [Programmable Current Limiting](#) section.

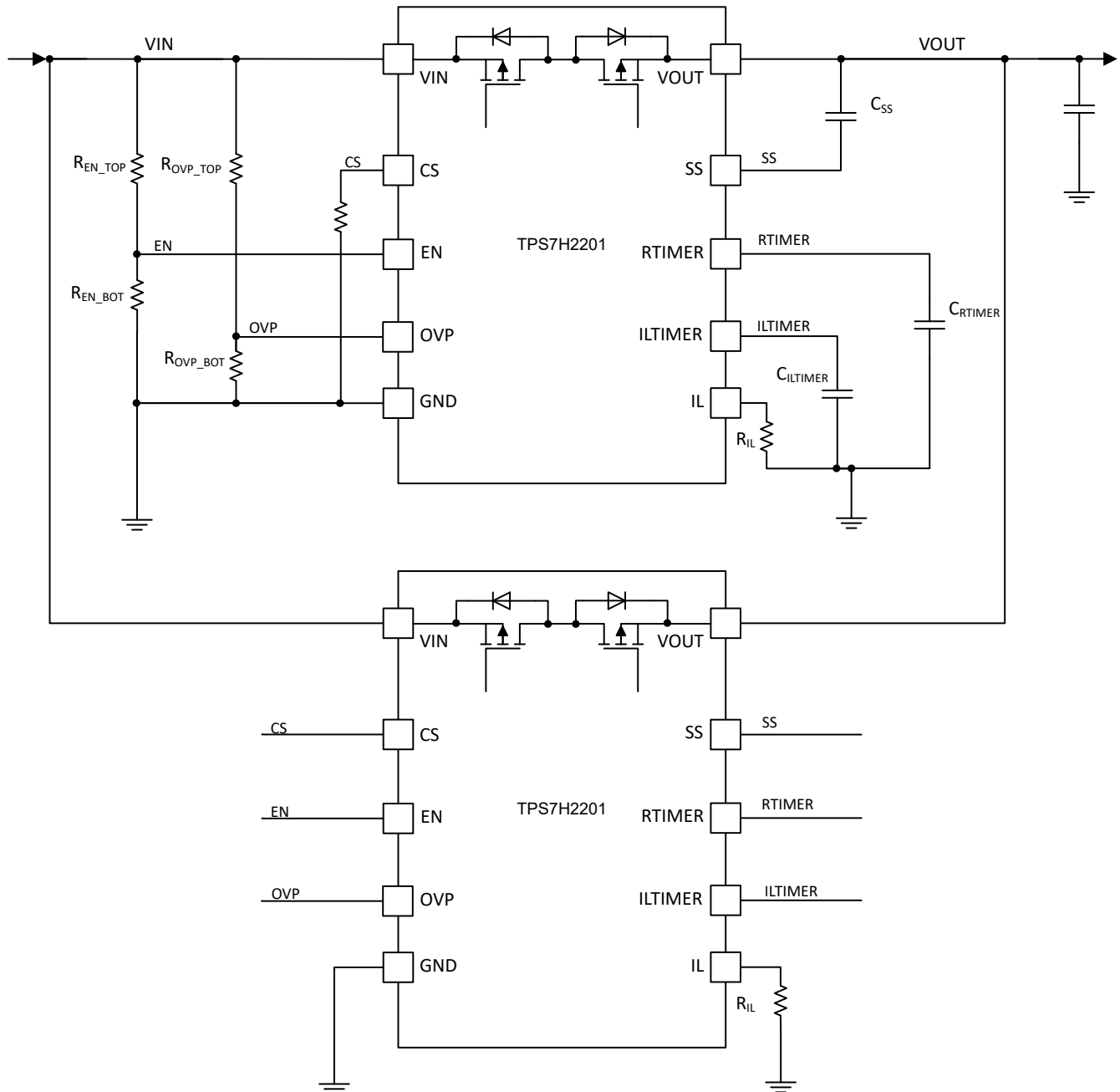


图 8-6. Parallel Configuration to Reduce Resistance or Increase Current Capability

8.3.7 Reverse Current Protection

The TPS72201 eFuse features back to back FETs to prevent current flow from VIN to VOUT and from VOUT to VIN when the switch is disabled (excluding leakage currents). This supports cold sparing (redundancy) applications. For example, VOUT may be up to 7 V while VIN is between 0 V and 7 V. In all cases, only small leakage current will result.

8.3.8 Forward Leakage Current

When VIN is powered but the TPS7H2201 is disabled (EN is low), the internal FETs are disabled, creating a high impedance path from VIN to VOUT. However, there are parasitic leakage paths that can cause VOUT to slowly charge. The forward leakage current, I_F , indicates how much current flows from VIN to VOUT during this situation. The maximum forward of the TPS7H2201-SP current is specified at 250 μ A across voltage, temperature and radiation.

Some applications need to pay particular attention to this behavior. Is particularly relevant when VOUT is a high impedance node (and therefore the leakage current goes entirely to charging VOUT instead of being dissipated). By using the basic capacitor equation shown in [方程式 11](#), the time for the voltage to rise to a given value can be theoretically calculated.

$$\Delta t = \Delta V_{OUT} \times C_{OUT} / I_F \quad (11)$$

where

- Δt = time to charge to final value
- ΔV_{OUT} = change in output voltage; for a 0 V starting voltage, use V_{IN}

For example, with a 7-V input voltage and a 220- μ F output capacitance, VOUT typically charge to 7 V in approximately 6.2 seconds (using $I_F = 150 \mu$ A, $\Delta V_{OUT} = 7$ V, $C_{OUT} = 220 \mu$ F).

If the output voltage must remain below a certain value, a pull-down resistor can be utilized with a value as calculated by using [方程式 12](#).

$$V_{OUT_LKG_MAX} = I_F \times R_{PULL_DOWN} \quad (12)$$

where

- $V_{OUT_LKG_MAX}$ = maximum output voltage due to leakage current, I_F
- R_{PULL_DOWN} = external pull-down resistor from VOUT to GND

For example, placing a 2.6-k Ω resistor between VOUT and ground makes sure VOUT does not rise above 0.65-V worst case due to the I_F current. The resistor need to be able to handle the worst case power dissipation when the switch is enabled and $V_{OUT} \approx V_{IN}$.

8.4 Device Functional Modes

VOUT Connection due to V_{EN} and V_{OVP} lists the VOUT pin state as determined by the EN and OVP pin voltages.

表 8-3. VOUT Connection due to V_{EN} and V_{OVP}

EN PIN	OVP PIN	TPS7H2201-SP and TPS7H2201-SEP ^{(5) (6)}
0 ⁽¹⁾	0 ⁽³⁾	Open
0	1 ⁽⁴⁾	Open
1 ⁽²⁾	0	VIN
1	1	Open

(1) $V_{EN} < V_{IEN(MIN)} = 0$

(2) $V_{EN} > V_{IHEN(MAX)} = 1$

(3) $V_{OVP} < V_{OVPF(MIN)} = 0$

(4) $V_{OVP} > V_{OVPR(MAX)} = 1$

(5) Refer to [Turn-On \(\$t_{ON}\$ \), Turn-Off \(\$t_{OFF}\$ \) and VOUT Fall Time \(\$t_F\$ \) Waveforms](#) for more details.

(6) Refer to [OVP Assert \(\$t_{ASSERT}\$ \) and OVP Deassert \(\$t_{DEASSERT}\$ \) Waveforms](#) for more details.

9 Application and Implementation

备注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The TPS7H2201 device is a single channel, 6-A eFuse with multiple programmable features such as current limit, undervoltage and overvoltage, current limit and retry timers, and soft start. In addition, the TPS7H2201 features a reverse current protection capability for power distribution applications and current sensing for load monitoring purpose. The TPS7H2201-SP user's guide is available on the TI website, [TPS7H2201EVM-CVAL Evaluation Module \(EVM\) User's Guide](#). The guide highlights standard EVM configurations, test results, schematic, and BOM for reference.

9.2 Typical Applications

In addition to the standard power management applications where a power switch can be used, there are 2 main applications in which the TPS7H2201 can be used in space power applications:

- Redundancy for primary and secondary voltage rails common in satellite applications
- Protection for critical or SEL sensitive loads

9.2.1 Redundancy

In applications where primary and secondary (redundant) power rails are present, the TPS7H2201 is ideal to implement redundancy because of its reverse current blocking capability. In this case, since the eFuse is placed at the input of the point of load regulator, the on-resistance of the switch is not as critical.

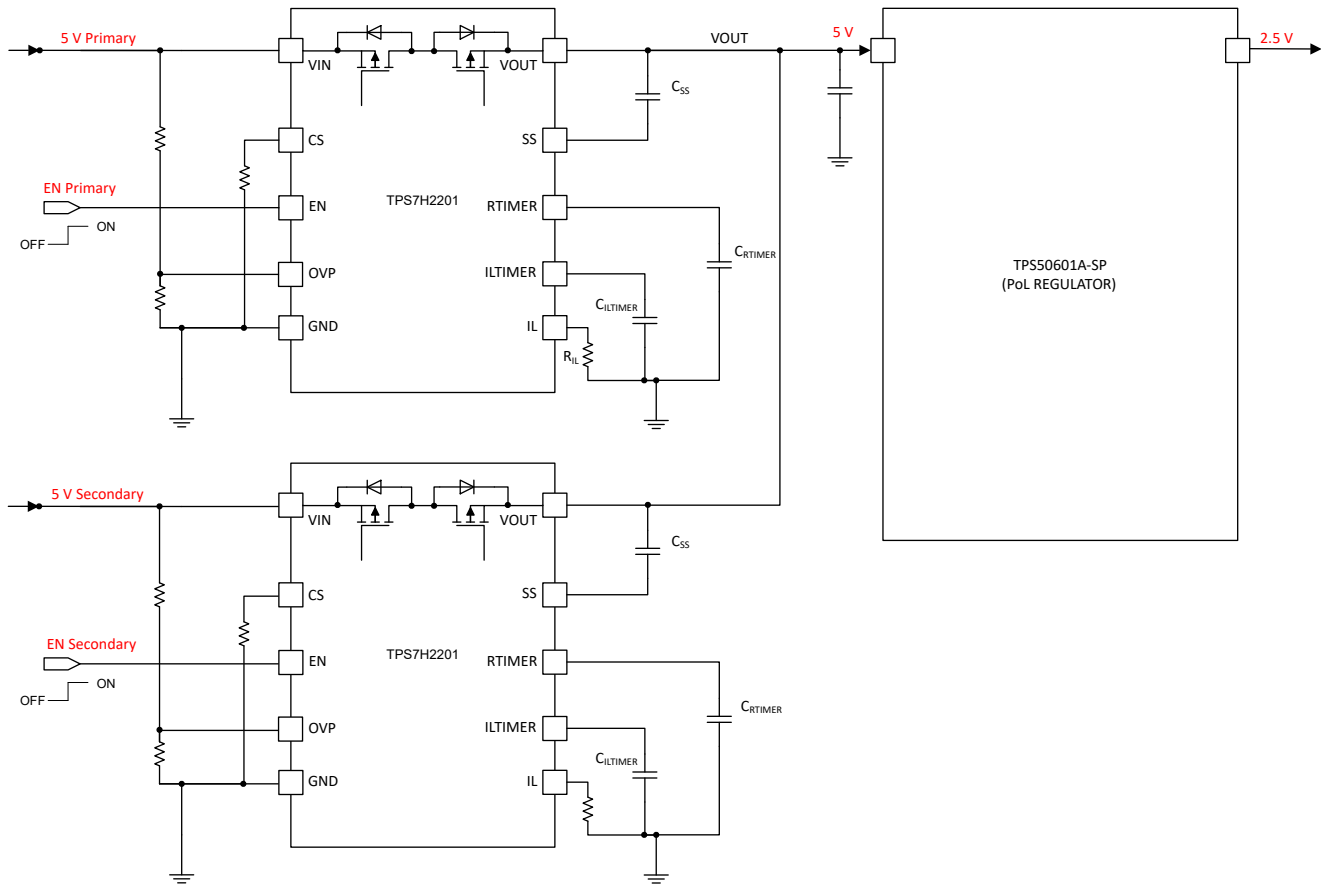


图 9-1. Redundancy Example Using the TPS7H2201

9.2.2 Protection

The protection features of the TPS7H2201 can also be used for SEL sensitive loads. In such case, the on-resistance of the switch might be more relevant as it is placed after the point of load regulator but in such case, two eFuse can be placed in parallel to reduce the on-resistance if needed. The main advantages of using the eFuse at this location is faster response to SEL events and automatic recovery due to the retry mode of the programmable fault timer.

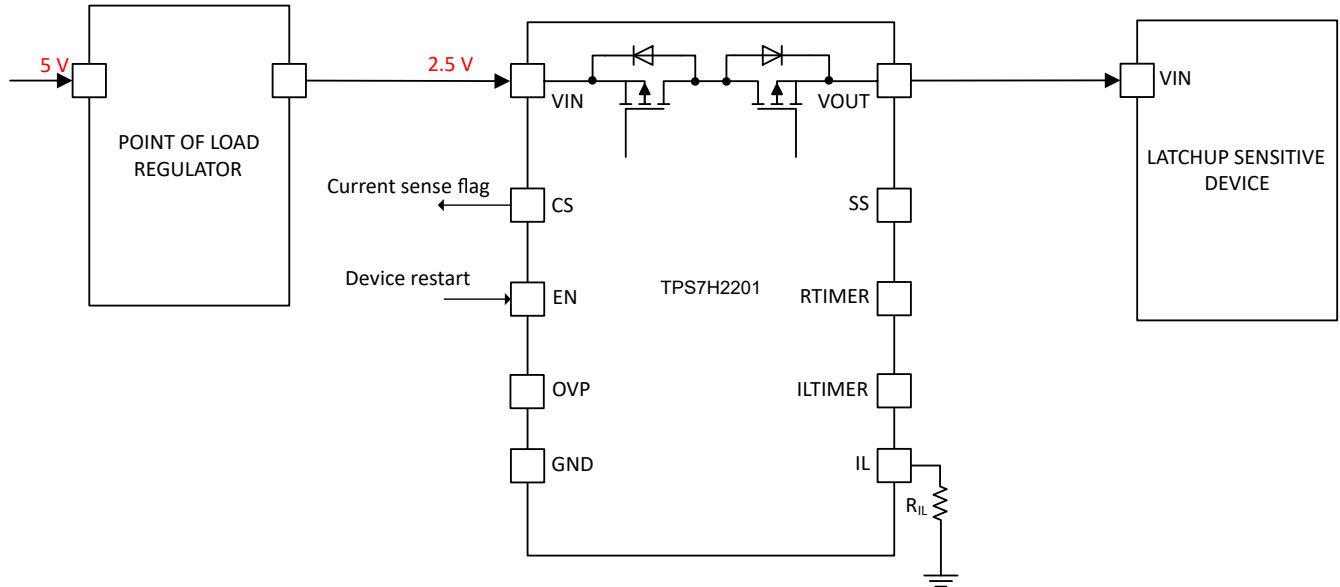


图 9-2. Protection Example Using the TPS7H2201

9.2.3 Design Requirements

图 9-3 shows a typical application schematic that is applicable to both the redundancy and the protection applications previously discussed.

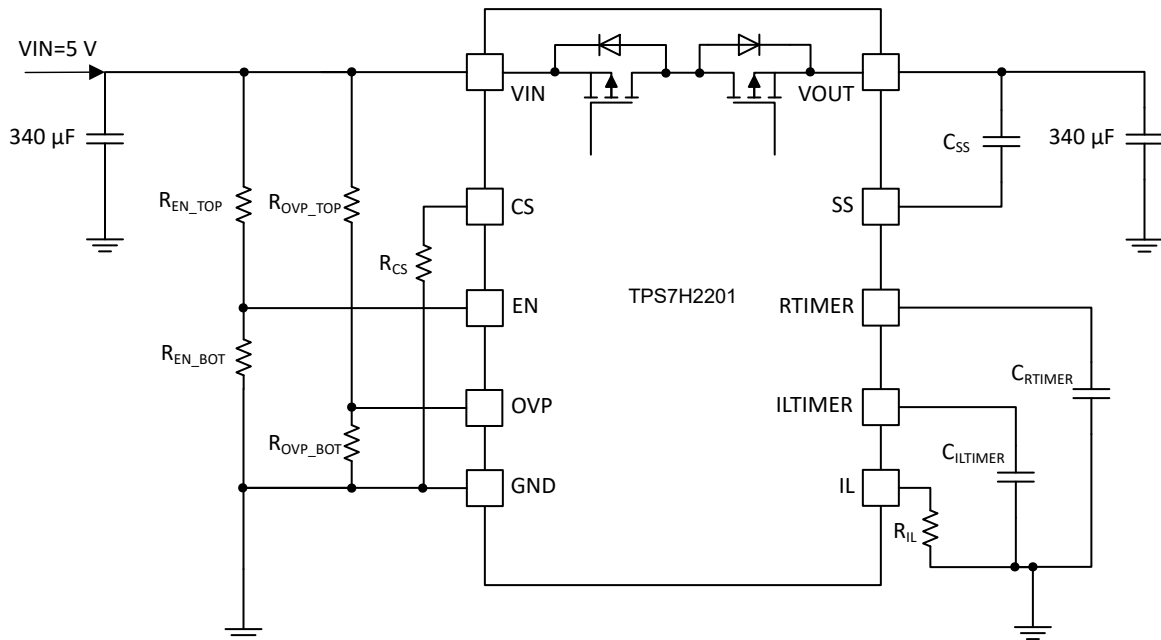


图 9-3. Typical Application Schematic

表 9-1 shows the design parameters.

表 9-1. Design Parameters

DESIGN PARAMETER	EXAMPLE VALUE
VIN	5 V
Undervoltage lockout set point	3.5 V

表 9-1. Design Parameters (续)

DESIGN PARAMETER	EXAMPLE VALUE
Overvoltage protection set point	6.5 V
Output current	6 A
Current limit	7.5 A
Current limit timer	1 ms
Retry timer	1 ms
Soft start time	9 ms
Input and output capacitors	340 µF

9.2.4 Detailed Design Procedure

9.2.4.1 Undervoltage Lockout

The undervoltage lockout set point is configured using the resistor divider, R_{EN_TOP} and R_{EN_BOT} connected to the EN pin. Set the $R_{EN_TOP} = 100\text{ k}\Omega$ and, using 方程式 1, calculate the value for R_{EN_BOT} . For an $UVLO = 3.5\text{ V}$, $R_{EN_BOT} = 15.5\text{ k}\Omega$. When choosing the UVLO set point, the resistor divider must ensure that the device will still get enabled for the VIN used in the application. This is achieved by making sure that the V_{IHEN} requirement is still met with the chosen resistor divider and that the VIN needed to meet the requirement is smaller than the VIN used in the application. 方程式 13 shows this VIN and V_{IHEN} requirement to set the UVLO point. For this particular application, the requirement is met as the result is 4.84 V.

$$V_{IHEN} \times \frac{R_{EN_TOP} + R_{EN_BOT}}{R_{EN_BOT}} \leq VIN \quad (13)$$

9.2.4.2 Overvoltage Protection

In a similar way to the UVLO set point, the overvoltage protection set point is configured using the resistor divider, R_{OVP_TOP} and R_{OVP_BOT} connected to the OVP pin. Set the $R_{OVP_TOP} = 100\text{ k}\Omega$ and, using 方程式 2, calculate the value for R_{OVP_BOT} . For an $OVP = 6.5\text{ V}$, $R_{OVP_BOT} = 10.7\text{ k}\Omega$. When choosing the OVP set point, the resistor divider must ensure that the device will still get enabled for the VIN used in the application. This is achieved by making sure that the V_{OVPF} requirement is still met with the chosen resistor divider and that the VIN needed to meet the requirement is larger than the VIN used in the application. 方程式 14 shows this VIN and V_{OVPF} requirement to set the OVP point. For this particular application, the requirement is met as the result is 5.16 V.

$$V_{OVPF} \times \frac{R_{OVP_TOP} + R_{OVP_BOT}}{R_{OVP_BOT}} \geq VIN \quad (14)$$

9.2.4.3 Current Limit

The current limit is configured using R_{IL} . Based on the output current for this design, the minimum current limit that can be programmed is $I_{OUT} + 1.5\text{ A}$ for a total of 7.5 A. As a result, using 方程式 8, the resistor value is $6.53\text{ k}\Omega$.

9.2.4.4 Programmable Fault Timers

The programmable fault timers are configured using the $C_{ILTIMER}$ and the C_{RTIMER} capacitors. For this particular design, both timers are set to 1 ms. Therefore, using 方程式 9, the value for each capacitor is 2000 pF. These capacitor values meet the requirement in 方程式 10.

9.2.4.5 Soft Start Time

The soft start time is configured using the C_{SS} capacitor. In order to calculate the value of the capacitor, the VOUT slew rate needs to be calculated using 方程式 3 to make sure the maximum VOUT slew rate requirement

shown in 方程式 4 is satisfied. This requirement is particularly important for space applications where large output capacitance is typically used, which translates to a lower maximum allowable VOUT slew rate. For this particular design, the VOUT slew rate is 555 V/s which is less than the maximum VOUT slew rate of 882 V/s, meeting the requirement from 方程式 4. Now, the soft start capacitor value can be calculated as 117 nF using 方程式 6, since VIN = 5 V for this application.

9.2.5 Application Curves

The power-up behavior of this design example is shown in 图 9-4 and the current limit behavior is shown in 图 9-5.

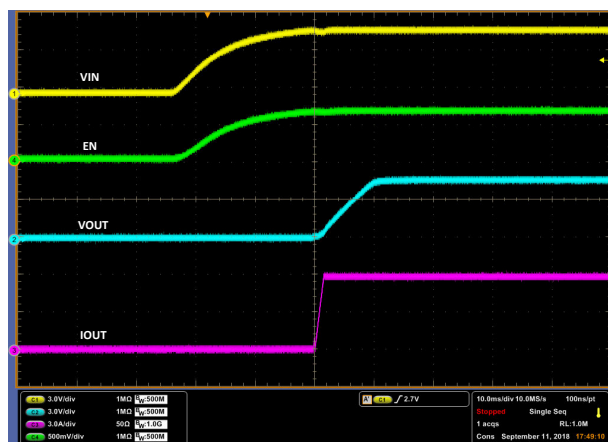


图 9-4. Power-up Behavior of the TPS7H2201-SP

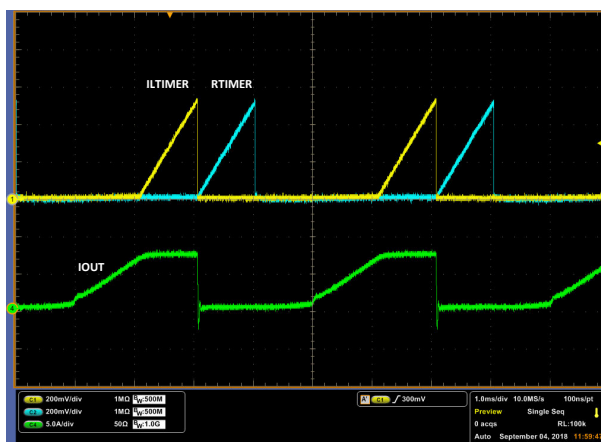


图 9-5. ILTIMER and RTIMER Waveforms When IL is Set to 7.5 A

9.3 Power Supply Recommendations

The TPS7H2201 is designed to operate from an input voltage supply range between 1.5 V to 7 V. This supply voltage must be well regulated and proper local bypass capacitors should be used for proper electrical performance from VIN to GND. Due to stringent requirements for space applications, typically numerous input bypass capacitors are used and the total capacitance is much larger than for commercial applications. The TPS7H2201-SP Evaluation Module uses one 330- μ F tantalum capacitor in parallel with one 10- μ F and one 0.1- μ F ceramic capacitor.

9.4 Layout

9.4.1 Layout Guidelines

For best performance, all traces should be as short as possible. To be most effective, the input and output capacitors should be placed close to the device to minimize the effects that parasitic trace inductances may have on normal operation. Using wide traces for VIN, VOUT, and GND helps minimize the parasitic electrical effects. In general, the components should be placed close to the device such that traces remain as short as possible to avoid parasitic capacitance. In addition, due to the possibility of large power dissipation in fault conditions (short at VOUT), thermal vias should be placed in the PCB for the thermal pad.

9.4.2 Layout Example

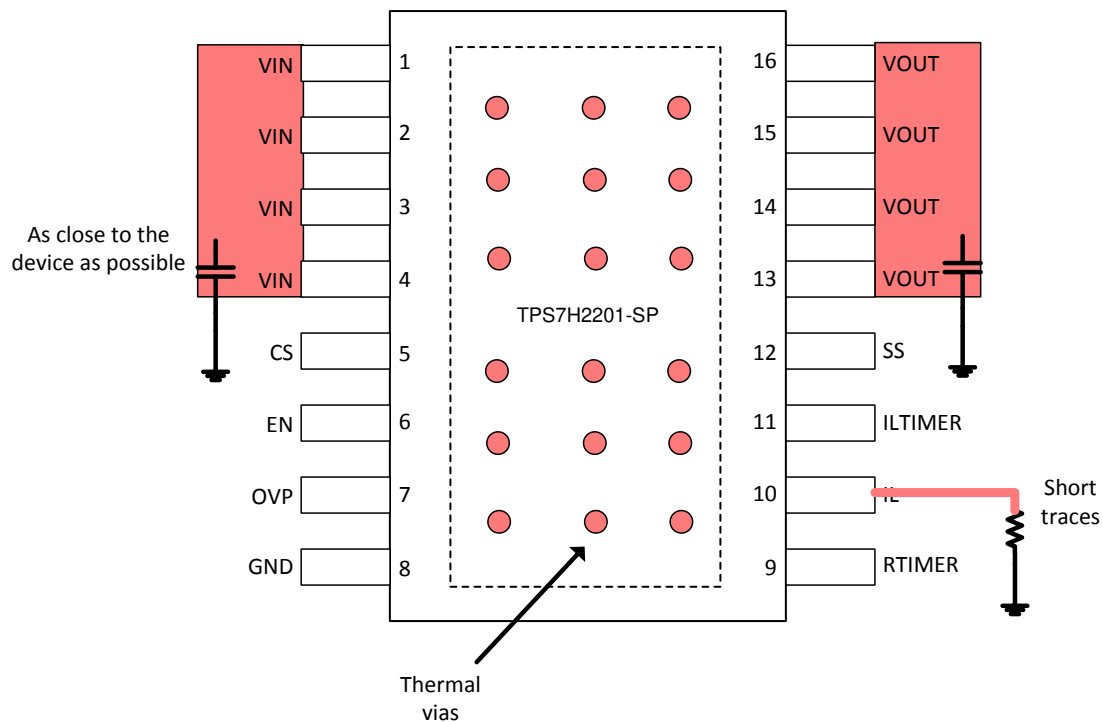


图 9-6. Layout Recommendation

10 Device and Documentation Support

10.1 Documentation Support

10.1.1 Related Documentation

For related documentation see the following:

- Texas Instruments, [TPS7H2201-SP Total Ionizing Dose \(TID\) Report](#)
- Texas Instruments, [TPS7H2201-SEP TID Radiation Report](#)
- Texas Instruments, [Single-Events Effects Test Report of the TPS7H2201-SP eFuse](#)
- Texas Instruments, [Single-Event-Effects Test Report of the TPS7H2201-SEP eFuse](#)
- Texas Instruments, [TPS7H2201-SP Neutron Displacement Damage Characterization](#)
- Texas Instruments, [TPS7H2201EVM-CVAL Evaluation Module \(EVM\) User's Guide](#)
- Texas Instruments, [TPS7H2201EVM Evaluation Module \(EVM\)](#)
- Texas Instruments, [Unencrypted PSpice Transient Model](#)
- Texas Instruments, [Load Switch Thermal Considerations](#)
- Texas Instruments, [Basics of eFuses](#)
- Texas Instruments, [Basics of Load Switches](#)
- [Standard Microcircuit Drawing, 5962R17220](#)
- [Vendor Item Drawing, V6223608](#)

10.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

10.3 支持资源

TI E2E™ 中文支持论坛是工程师的重要参考资料，可直接从专家处获得快速、经过验证的解答和设计帮助。搜索现有解答或提出自己的问题，获得所需的快速设计帮助。

链接的内容由各个贡献者“按原样”提供。这些内容并不构成 TI 技术规范，并且不一定反映 TI 的观点；请参阅 TI 的[使用条款](#)。

10.4 Trademarks

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10.5 静电放电警告



静电放电 (ESD) 会损坏这个集成电路。德州仪器 (TI) 建议通过适当的预防措施处理所有集成电路。如果不遵守正确的处理和安装程序，可能会损坏集成电路。

ESD 的损坏小至导致微小的性能降级，大至整个器件故障。精密的集成电路可能更容易受到损坏，这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

10.6 术语表

TI 术语表 本术语表列出并解释了术语、首字母缩略词和定义。

11 Revision History

注：以前版本的页码可能与当前版本的页码不同

Changes from Revision E (December 2023) to Revision F (March 2024)	Page
--	------

- | | |
|--|---|
| • 删除了说明和器件选项部分中的 TPS7H2201MDAPTSEP 预告信息说明..... | 1 |
|--|---|

Changes from Revision D (September 2023) to Revision E (December 2023)	Page
--	------

- | | |
|---|---|
| • 在说明和器件选项部分中添加了 TPS7H2201MDAPTSEP 的预告信息说明..... | 1 |
|---|---|

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
5962-1722001VXC	ACTIVE	CFP	HKR	16	25	RoHS-Exempt & Green	NIAU	N / A for Pkg Type	-55 to 125	5962-1722001VXC TPS7H2201MHKRV	Samples
5962R1722001V9A	ACTIVE	XCEPT	KGD	0	25	RoHS & Green	Call TI	N / A for Pkg Type	-55 to 125		Samples
5962R1722001VXC	ACTIVE	CFP	HKR	16	25	RoHS-Exempt & Green	NIAU	N / A for Pkg Type	-55 to 125	5962R1722001VXC TPS7H2201MHKRV	Samples
5962R1722002PYE	ACTIVE	HTSSOP	DAP	32	250	RoHS & Green	NIPDAU	Level-3-260C-168 HR	-55 to 125	1722002PYE	Samples
TPS7H2201HKR/EM	ACTIVE	CFP	HKR	16	25	RoHS-Exempt & Green	NIAU	N / A for Pkg Type	25 to 25	TPS7H2201HKREM	Samples
TPS7H2201MDAPTSEP	ACTIVE	HTSSOP	DAP	32	250	RoHS & Green	NIPDAU	Level-3-260C-168 HR	-55 to 125	TPS7H2201	Samples
TPS7H2201Y/EM	ACTIVE	XCEPT	KGD	0	5	RoHS & Green	Call TI	N / A for Pkg Type	25 to 25		Samples
V62/23608-01XE	ACTIVE	HTSSOP	DAP	32	250	RoHS & Green	NIPDAU	Level-3-260C-168 HR		TPS7H2201	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

⁽⁵⁾ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

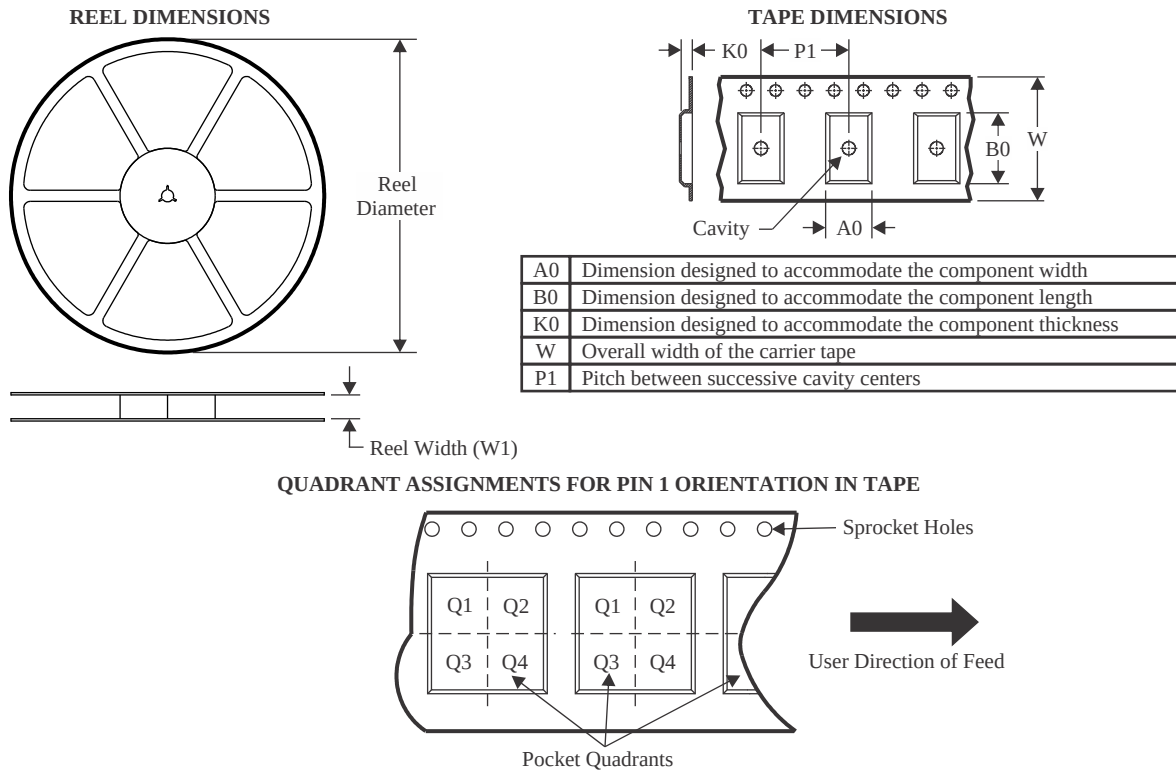
OTHER QUALIFIED VERSIONS OF TPS7H2201-SEP, TPS7H2201-SP :

- Catalog : [TPS7H2201-SEP](#)
- Space : [TPS7H2201-SP](#)

NOTE: Qualified Version Definitions:

- Catalog - TI's standard catalog product
- Space - Radiation tolerant, ceramic packaging and qualified for use in Space-based application

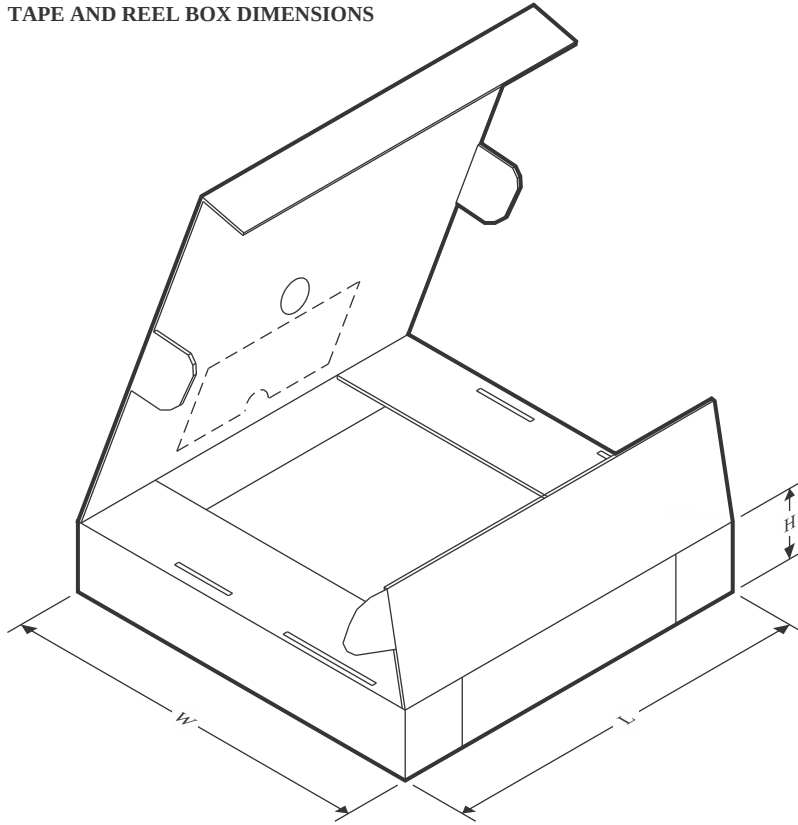
TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
5962R1722002PYE	HTSSOP	DAP	32	250	178.0	24.4	8.8	11.8	1.8	12.0	24.0	Q1
TPS7H2201MDAPTSEP	HTSSOP	DAP	32	250	330.0	24.4	8.8	11.8	1.8	12.0	24.0	Q1

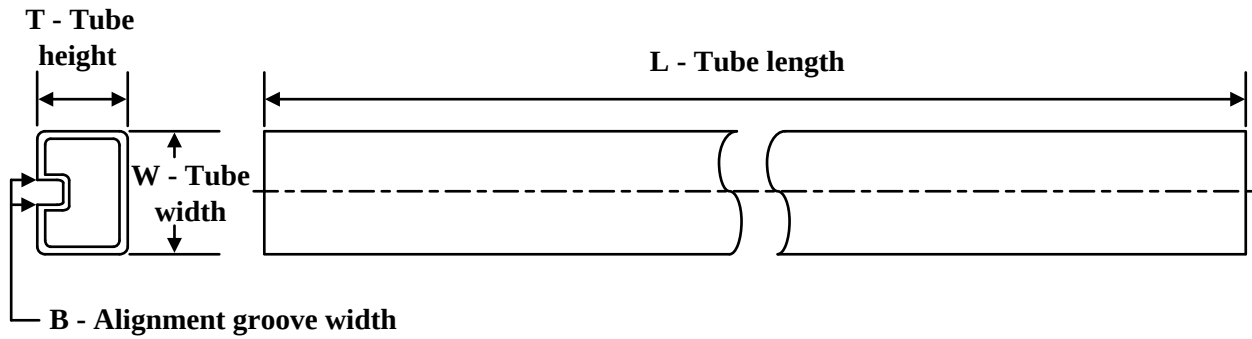
TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
5962R1722002PYE	HTSSOP	DAP	32	250	223.0	191.0	55.0
TPS7H2201MDAPTSEP	HTSSOP	DAP	32	250	356.0	356.0	41.0

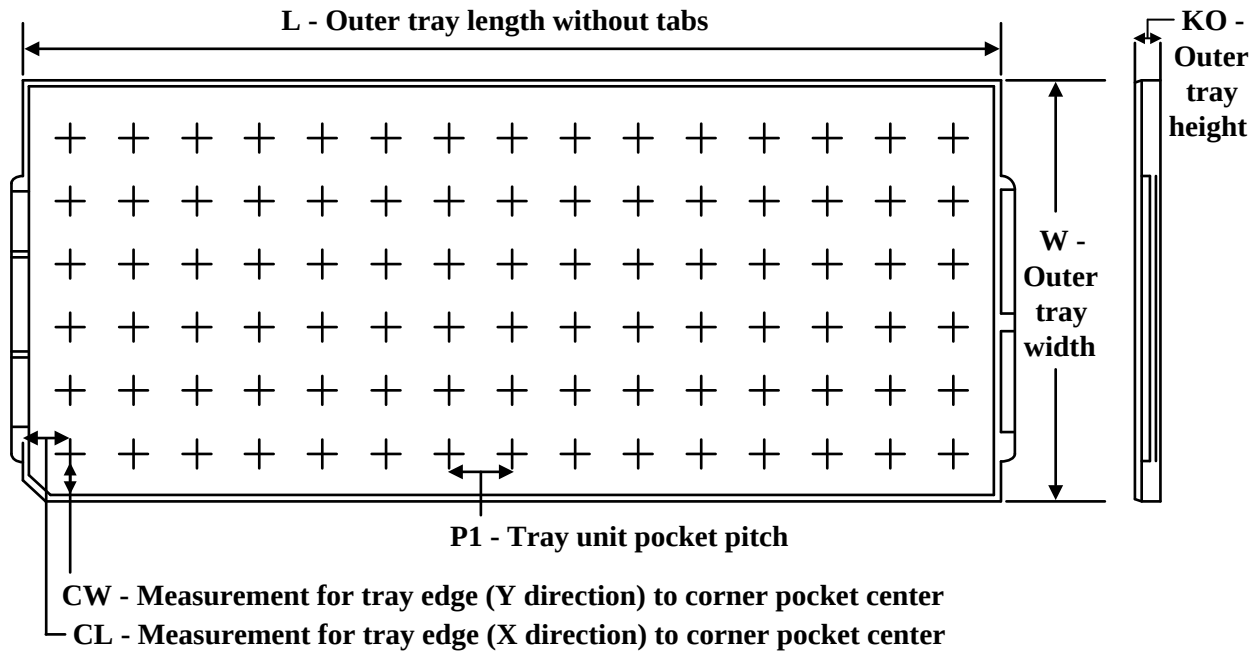
TUBE



*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
5962-1722001VXC	HKR	CFP	16	25	506.98	26.16	6220	NA
5962R1722001VXC	HKR	CFP	16	25	506.98	26.16	6220	NA
TPS7H2201HKR/EM	HKR	CFP	16	25	506.98	26.16	6220	NA

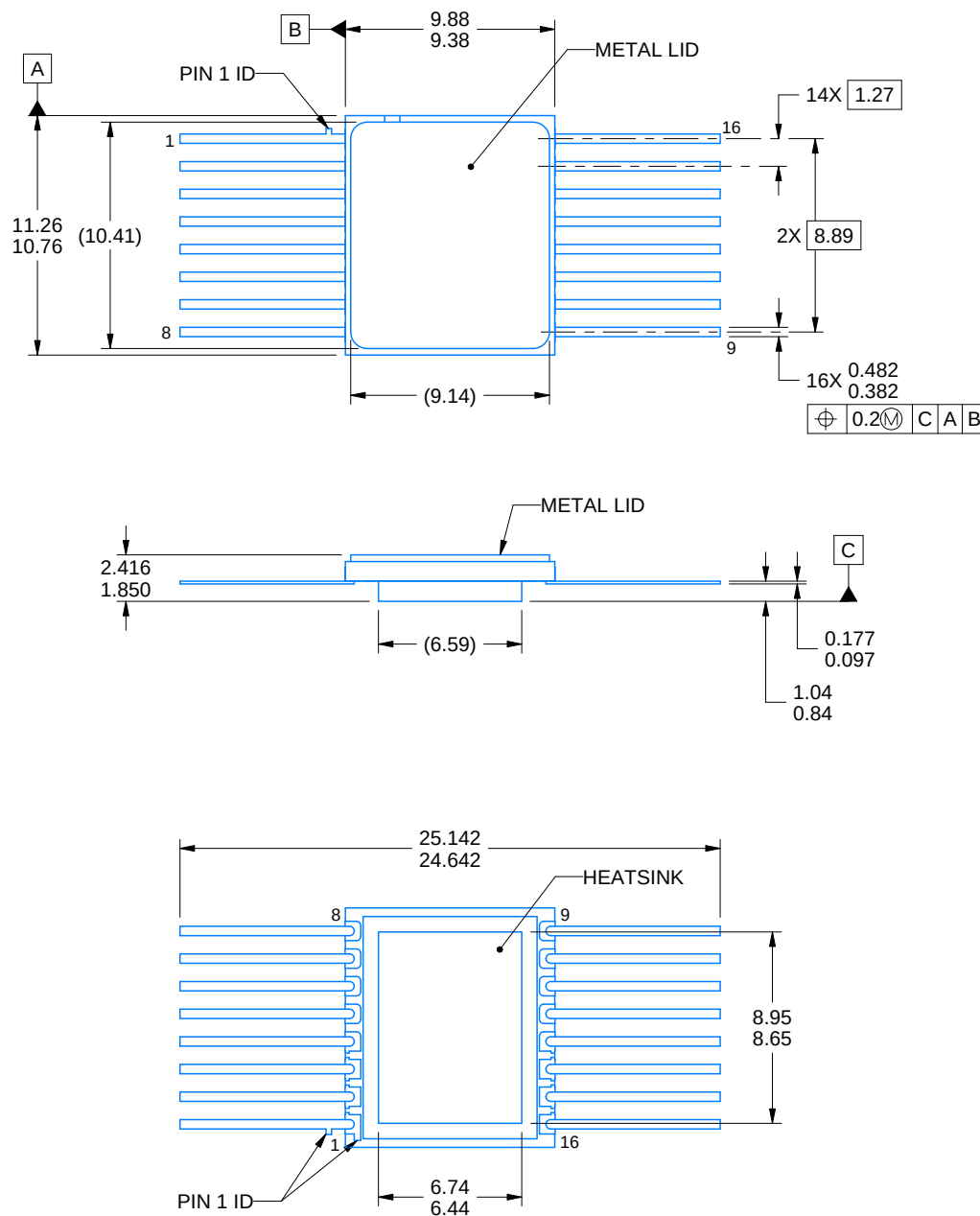
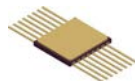
TRAY



Chamfer on Tray corner indicates Pin 1 orientation of packed units.

*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	Unit array matrix	Max temperature (°C)	L (mm)	W (mm)	K0 (μm)	P1 (mm)	CL (mm)	CW (mm)
TPS7H2201Y/EM	KGD	XCEPT	0	5	5 x 5	70	6.35	3.81	610	1.3	8.89	8.13



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NOTES:

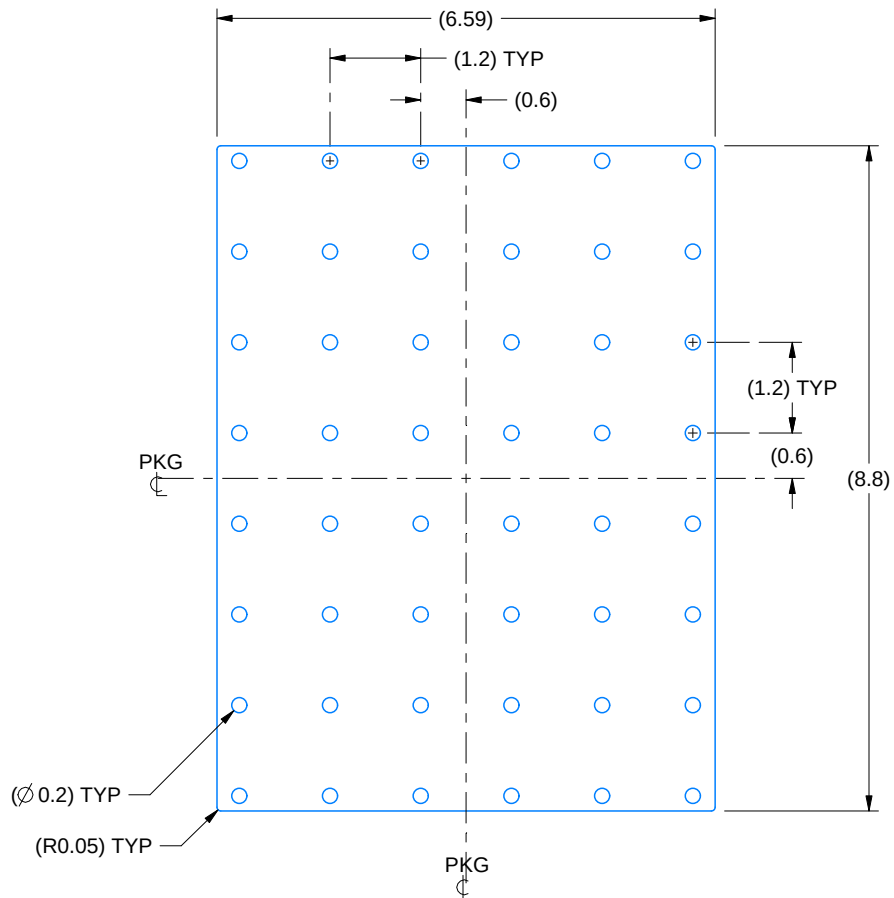
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This package is hermetically sealed with a metal lid. Lid is connected to Heatsink.
4. The terminals are gold plated.
5. Falls within MIL-STD-1835 CDFP-F11A.

EXAMPLE BOARD LAYOUT

HKR0016A

CFP - 2.416 mm max height

CERAMIC DUAL FLATPACK



HEATSINK LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:10X

4226020/C 08/2022

GENERIC PACKAGE VIEW

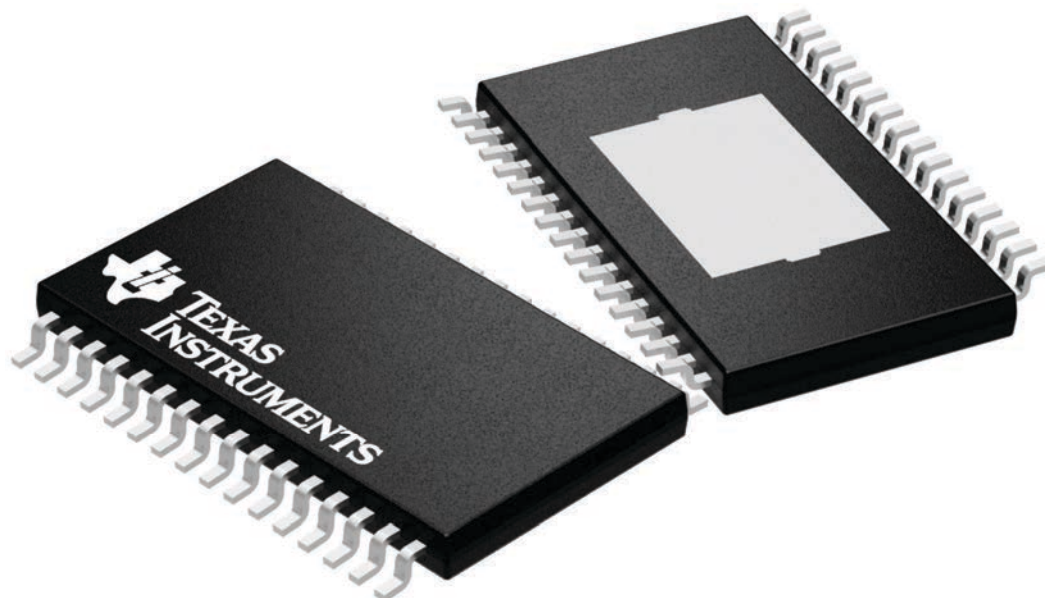
DAP 32

PowerPAD™ TSSOP - 1.2 mm max height

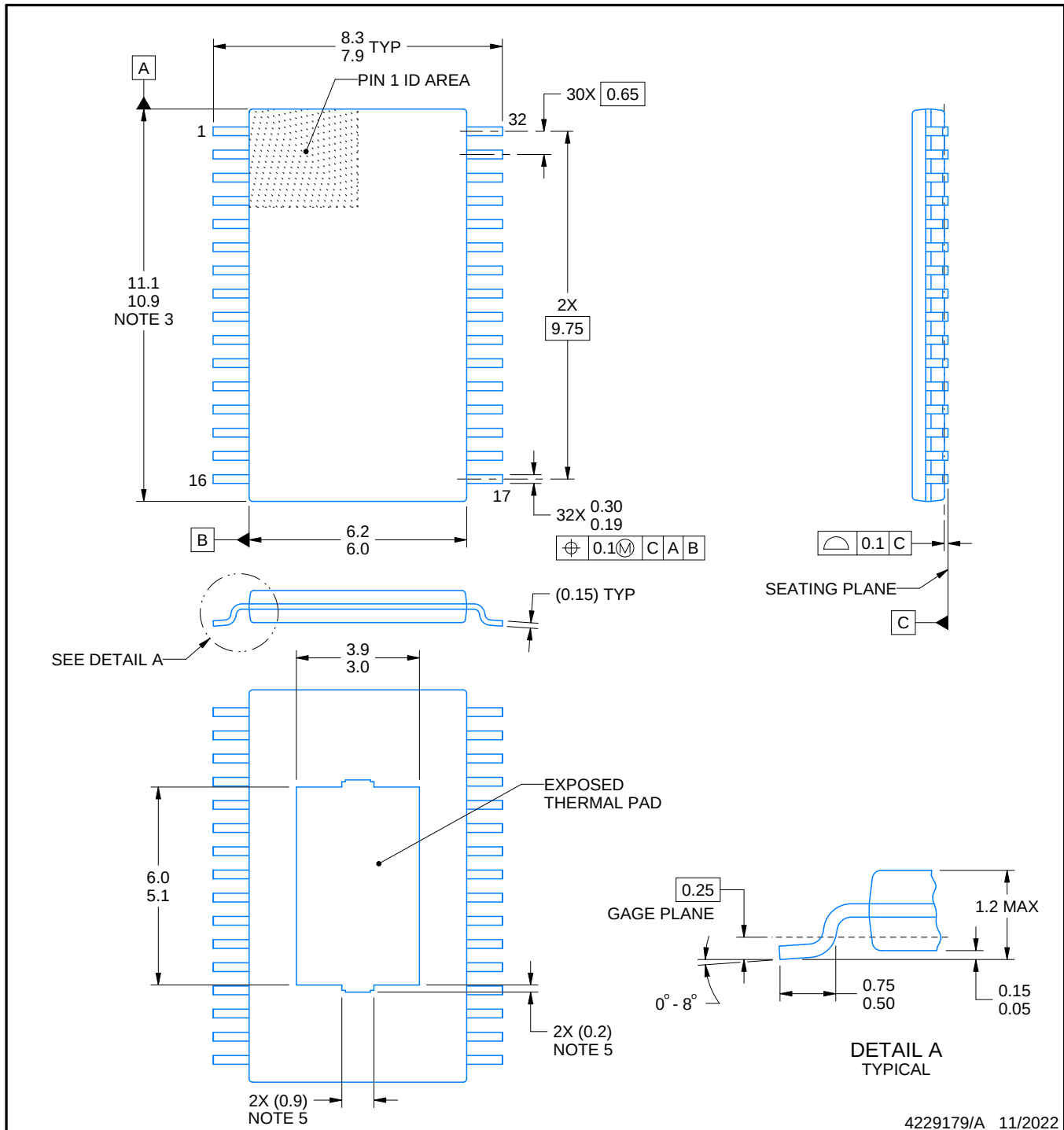
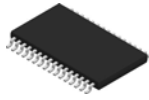
8.1 x 11, 0.65 mm pitch

PLASTIC SMALL OUTLINE

This image is a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.



4225303/A



4229179/A 11/2022

NOTES:

PowerPAD is a trademark of Texas Instruments.

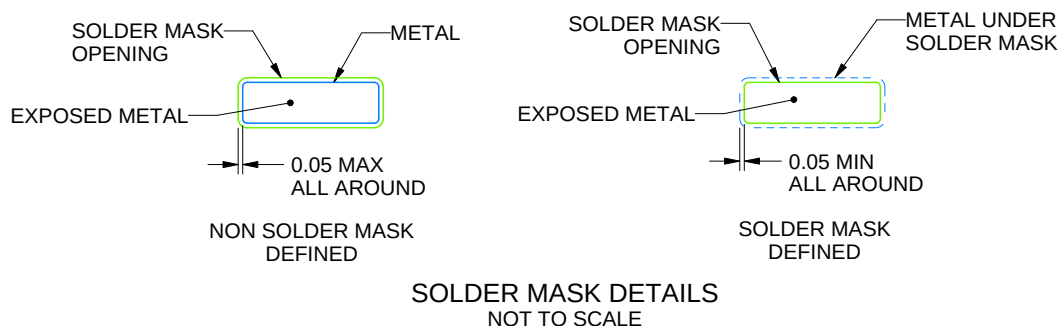
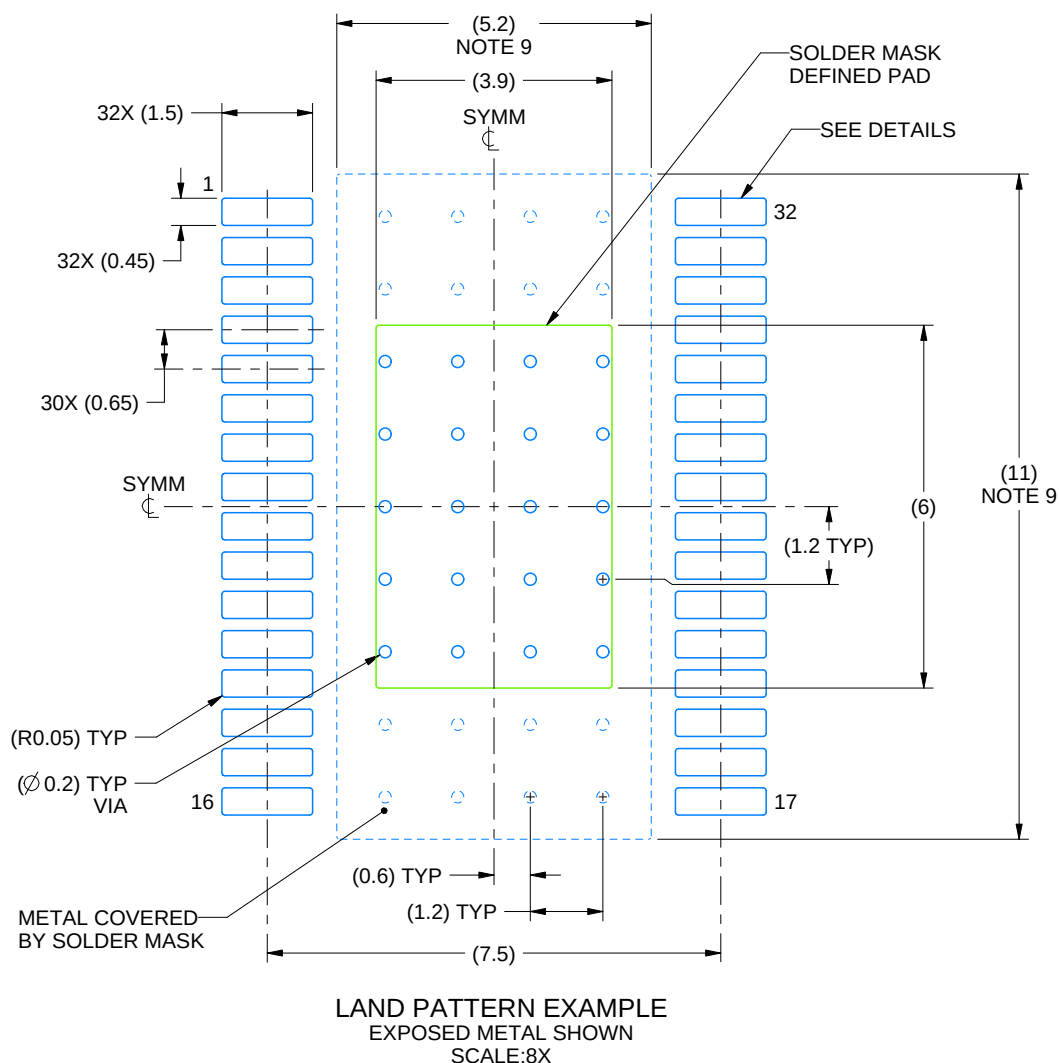
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. Reference JEDEC registration MO-153.
5. Features may differ and may not be present.

EXAMPLE BOARD LAYOUT

DAP0032G

PowerPAD™ TSSOP - 1.2 mm max height

PLASTIC SMALL OUTLINE



4229179/A 11/2022

NOTES: (continued)

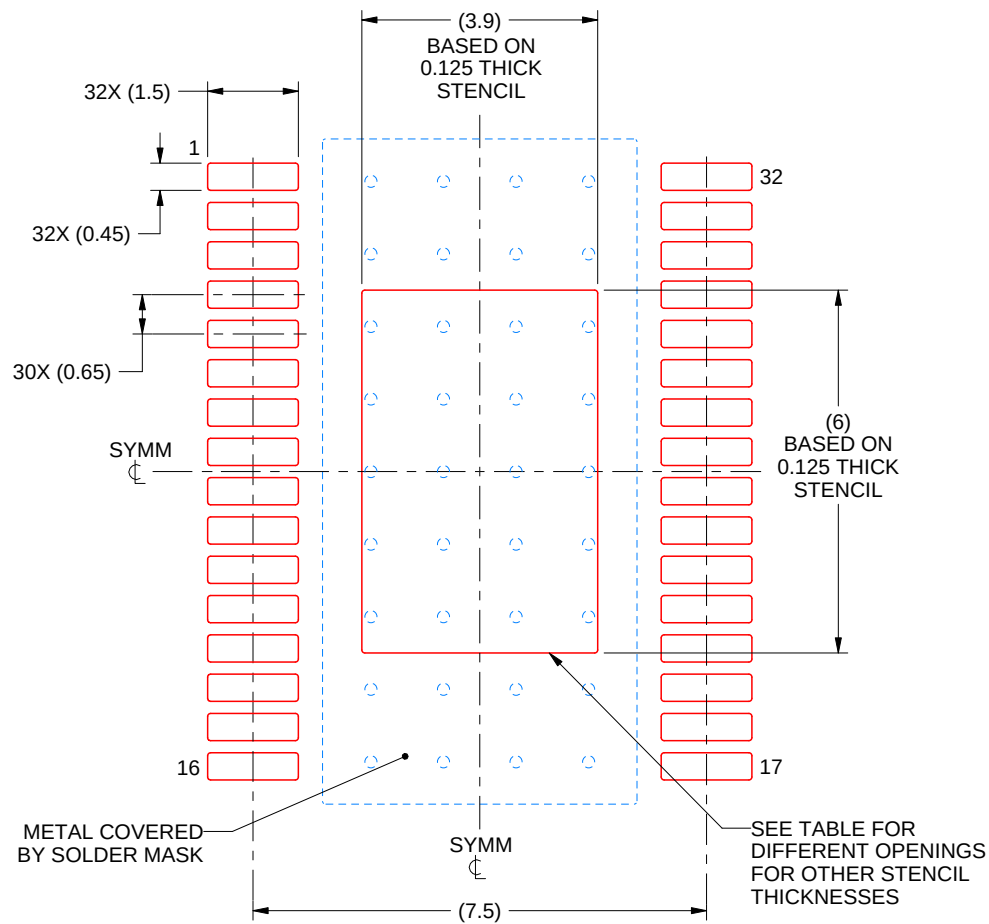
6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
8. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature numbers SLMA002 (www.ti.com/lit/slma002) and SLMA004 (www.ti.com/lit/slma004).
9. Size of metal pad may vary due to creepage requirement.

EXAMPLE STENCIL DESIGN

DAP0032G

PowerPAD™ TSSOP - 1.2 mm max height

PLASTIC SMALL OUTLINE



SOLDER PASTE EXAMPLE
EXPOSED PAD
100% PRINTED SOLDER COVERAGE BY AREA
SCALE:8X

STENCIL THICKNESS	SOLDER STENCIL OPENING
0.1	4.36 X 6.71
0.125	3.90 X 6.00 (SHOWN)
0.15	3.56 X 5.48
0.175	3.30 X 5.07

4229179/A 11/2022

NOTES: (continued)

10. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
11. Board assembly site may have different recommendations for stencil design.

重要声明和免责声明

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